

# Medical Imaging in IMRT Planning

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## Overview

- RT as image guided therapy
- Imaging in the RT process
- Modalities
  - anatomical
  - functional / molecular
- Image registration and fusion
- Segmentation
- Image communication: DICOM, DICOM-RT, RTOG

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## IMRT is image guided therapy

- maybe even the original image guided therapy!
- Reinstein, McShan mid-late 1970's showed 3D image guidance (e.g., BEV) could allow critical organ sparing
- JCRT group same time period used computer controlled linac to conform dose to target, avoid normal structures from image based patient model

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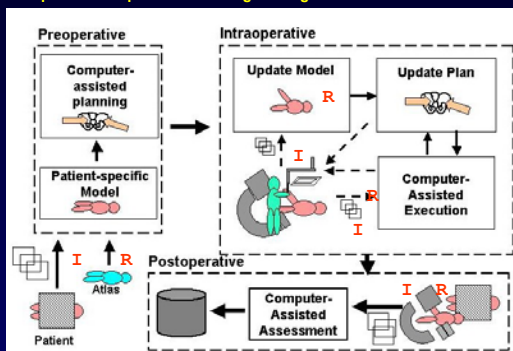
## Imaging for therapy guidance

- Stages of guidance
  - planning
  - setup
  - real time guidance
  - real time feedback (typically not, in RT)
  - adaptation of multiple treatments
  - assessment of effect
  - followup
- Not every application uses all of these, but RT uses nearly every one.

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Information flow in computer integrated surgery: R.H. Taylor, Johns Hopkins CS Dept and CISST Engineering Research Center



I: Imaging R: Registration

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## • Planning stage: what do we need? Target and organs at risk

- anatomy: usual scan gives a snapshot (with a slow shutter speed!)
  - dynamic scanning to get a movie
  - gated acquisition to get a freeze frame
- functional information, e.g. important brain areas, functional lung, bioimaging for tumor
  - registration methods; data communication; new image modalities
- sensitivity is paramount – must identify all the tumor<sup>1</sup>
  - multimodality imaging; registration
- specificity is desirable – want to avoid complications

<sup>1</sup>F. Jolesz, in Oncologic Imaging, Bragg et al., Chap. 4

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- Setup stage: what do we need? rapid registration of plan ("virtual patient") with the actual patient in treatment room
  - registration methods; data communication; position measurement / tracking; display technologies; imaging technologies (radiographs? video?); validation/QA (accuracy!)
- registration of treatment device with both virtual patient and interactive imaging system(s)
  - multiview radiography to register with 3D patient model? 2D/3D registration; registration of radiography and US;
- note external beam RT has similar issues as robotic procedures

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- Real time guidance: hit a moving target
  - gating
    - based on direct physiologic signal (e.g., spirometer)
    - based on images (e.g., video or IR fiducials)
  - "4D" treatment – attempt to follow motion of anatomy
    - actual anatomy
    - inferred position from dynamic model synchronized with gating signal
  - (re) registration methods; data communication; position measurement / tracking; display technologies; image fusion; correction of planning images / plan as procedure changes anatomy?

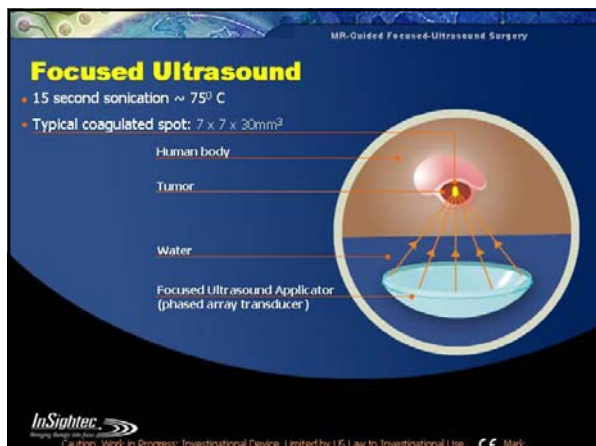
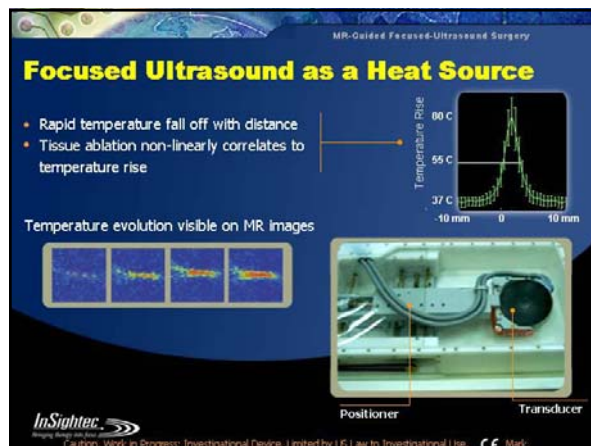
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- Real time feedback example: MR guided focused US tissue ablation
  - rapid image acquisition and display during treatment
  - comparison of actually treated region with plan
- Analog in RT: intratreatment dose determination with portal imager – accumulating dose to patient model as Tx is delivered. Not as direct as thermal MR imaging in FUS

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MR-Guided Focused-Ultrasound Surgery

## Step 2: Treatment

During energy delivery of every sonication

- System acquires thermal **MR images**; Shows sonication location and anatomy
- System computes temperature map
- User adjusts parameters to achieve desired outcome



**InSightec**  
imaging through the power of ultrasound  
 Caution, Work in Progress: Investigational Device. Limited by US Law to Investigational Use. CE Mark:

MR-Guided Focused-Ultrasound Surgery

## Step 3: Outcome Assessment

After Treatment

- **MR contrast enhanced images** identify change in contrast uptake to provide feedback on treatment effect



**InSightec**  
imaging through the power of ultrasound  
 Caution, Work in Progress: Investigational Device. Limited by US Law to Investigational Use. CE Mark:

- Adaptation of fractionated treatments:  
 Adaptive radiotherapy
  - problem: fractionated treatment over weeks
  - intra and inter fraction targeting errors
    - patient pose (setup) variation
    - variation in anatomy – organ motion
  - approach: image at each fraction, infer range of uncertainties. Adapt subsequent fractions. At some point stop imaging – diminishing return
    - imaging methods; anatomical modeling from images; biomechanics of organ motion; optimization of corrections; decision theory

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- Assessment
  - what is the signature of successful vs unsuccessful treatment?
    - anatomical changes
    - functional changes from familiar modalities
      - registration; image processing; data communication; display / analysis; validation / QA (get the right answer!)
    - evidence from new functional modalities
      - macro/meso/micro scale registration / fusion; handling large datasets; validation/QA (what does it mean?); detailed investigation of biological content of imaging evidence

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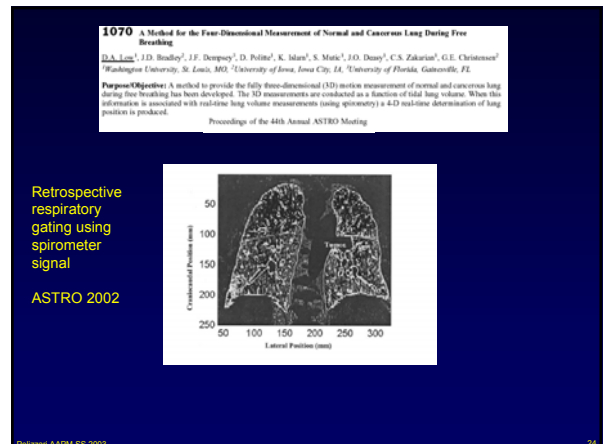
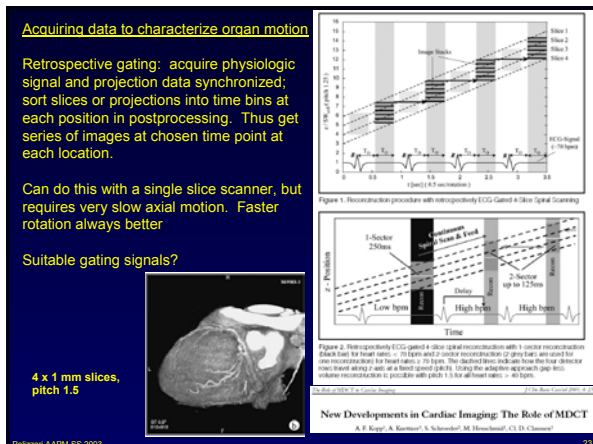
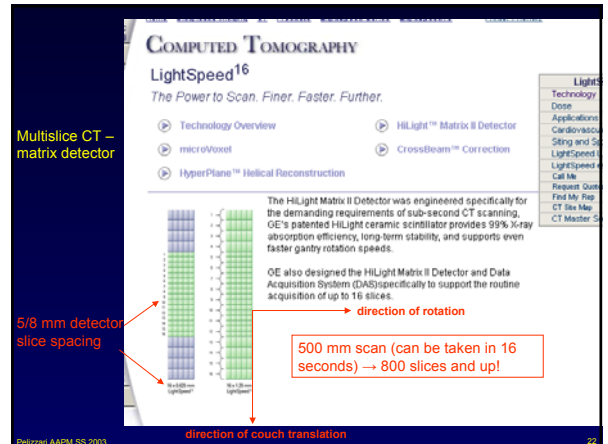
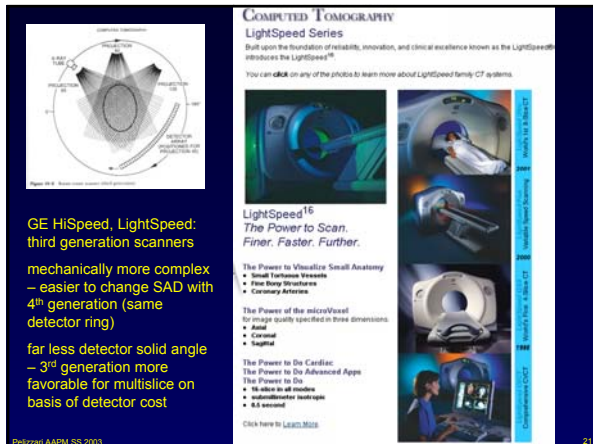
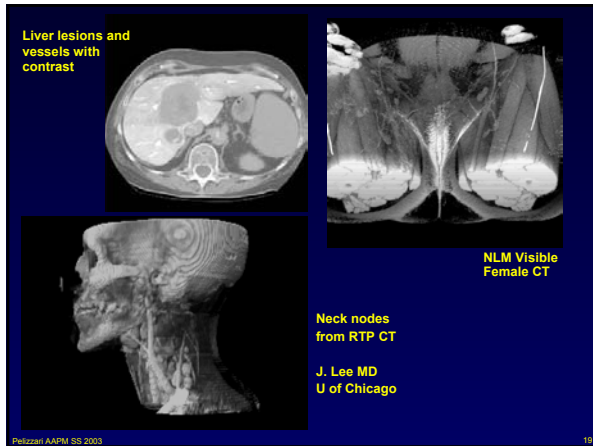
- Followup
  - serial imaging over time contributes to monitoring of patient status, robustness of response
    - anatomical imaging
    - old and new functional modalities
    - need to register retrospectively

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## Anatomical Modalities

- Advantages of CT
  - widely available; (relatively) inexpensive
  - good geometric accuracy
  - visualization of bony anatomy for comparison with radiographs (DRR)
  - potential for rapid scanning
  - siting issues not difficult
  - with contrast, many tumors and nodes visualized reasonably well

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## Anatomical modalities

- Advantages of MRI
  - no patient radiation dose
  - unparalleled soft tissue delineation
  - vast flexibility in imaging protocols – optimize for tissue of interest
  - multiparameter imaging in single coordinate system
  - adjustable resolution with specialized head, body, endorectal, etc. coils
  - vascular imaging with contrast agents
  - functional imaging capability (e.g. BOLD fMRI)
  - molecular imaging capability (spectroscopy and more)
  - ability to infer temperature, diffusion coefficient, diffusion tensor, etc.

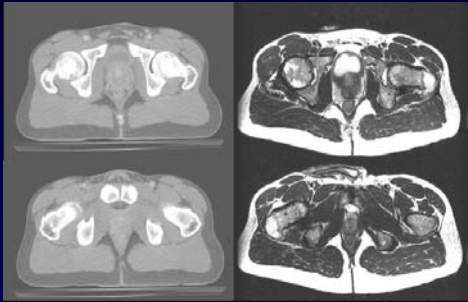


Figure 3. CT (left) and MR slices through approximately corresponding sections near the middle (above) and apex (below) of the prostate. Image parameters: CT, 5mm slice thickness, single-slice axial acquisition mode, 0.78 mm pixel size; MR, 4.5 mm slice thickness, 0.74 mm pixel size.

### Open magnet

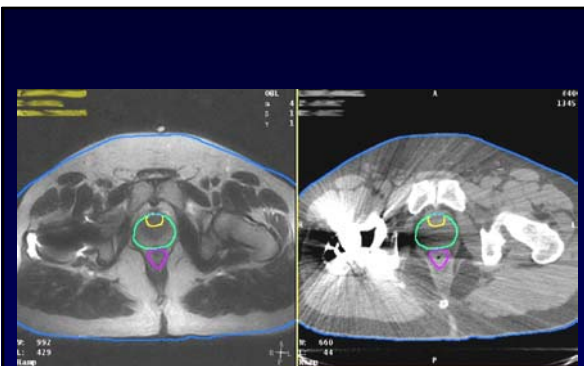
Plus: good access, easier to scan patient immobilized

Minus: low field – no spectroscopy, lower ultimate spatial resolution, more prone to field distortion artifacts



## Functional and Molecular Imaging

- Refine target identification
  - tumor vs normal tissue
  - clarify ambiguities, e.g. vs edema in MRI
  - active vs necrotic tumor regions
  - estimate cell density – use IMRT to optimize dose distribution
  - hypoxic vs necrotic regions – increase dose?
- Refine organ at risk definition
  - spare important functional areas, e.g. lung, brain regions
- Assessment
  - early feedback on treatment success – "signature" of Tx effect
    - molecular
    - genetic
    - vascular
    - others / combinations
  - adapt subsequent treatment based on this assessment?

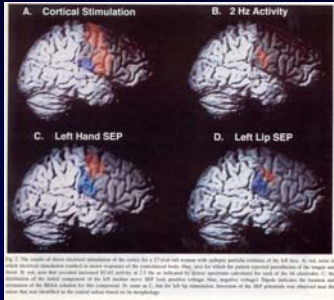
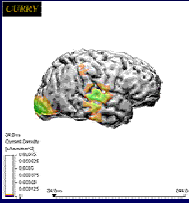


Philips 0.23T open MRI



Nontraditional (for RTP at least) sources of functional information can be integrated into the planning process via image or patient-image registration.

High-res EEG maps regions involved in stimulus response (NeuroScan Inc)



EEG Evoked potentials delineate motor and sensory cortex (Leo Towle, U of C)

### Molecular imaging with MRI – spectroscopic imaging

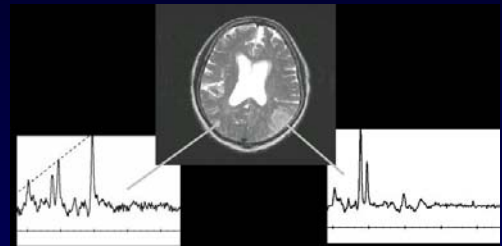


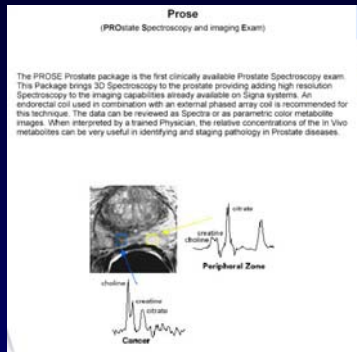
Figure 9. T2-weighted brain image with spectra from normal and tumor regions. The normal linearly increasing relationship between several spectral peaks on the left is absent on the right, indicative of tumor. (Image courtesy of P. MacEneaney, MD, University of Chicago)

### UCSF / GEMS

Choline/Citrate as indicator of malignancy

Use in tumor localization

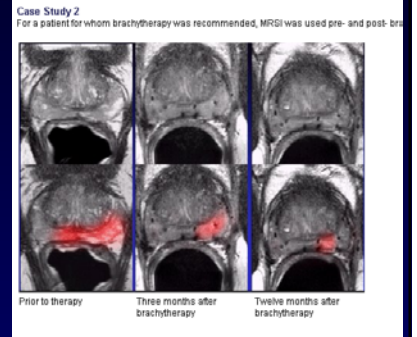
MAGNETIC RESONANCE IMAGING  
Signa Infinity 1.5T  
Prostate Spectroscopy Imaging Exam  
Julia Ruchmanowicz, Ph.D.  
Research Fellow, Radiology, UCSF



### UCSF / GEMS

Choline/Citrate as indicator of malignancy

Use in treatment assessment



### In vivo magnetic resonance imaging of transgene expression

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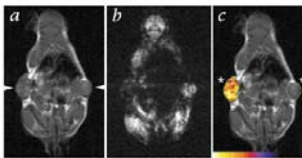


Fig. 3. In vivo MR imaging of a single mouse with ETR<sup>+</sup> (left arrowhead) and ETR<sup>-</sup> (right arrowhead) flank tumors. **a**, T1-weighted coronal SE image (imaging time, 1.5 min; voxel resolution, 500 × 500 × 5000 μm). ETR<sup>+</sup> and ETR<sup>-</sup> tumors have similar signal intensities. **b**, T2-weighted gradient echo image corresponding to the image in **a**, showing substantial differences between ETR<sup>+</sup> and ETR<sup>-</sup> tumors (imaging time, 8 min; voxel resolution, 300 × 300 × 3000 μm). As expected, ETR-mediated cellular accumulation of the superparamagnetic probe decreases signal intensity.

Monocrystalline iron oxide nanoparticles (MIONs) conjugated with transferrin; tumors engineered to express (or not) gene for transferrin receptor (ETR<sup>+</sup>/ETR<sup>-</sup>). MIONs accumulate in ETR<sup>+</sup> tumor on left, decrease T2\* and signal intensity.

### PET-GUIDED IMRT FOR CERVICAL CARCINOMA WITH POSITIVE PARA-AORTIC LYMPH NODES—A DOSE-ESCALATION TREATMENT PLANNING STUDY

SARA MUTIC, M.S.,<sup>1</sup> ROBERT S. MALLAPU, M.D., Ph.D.,<sup>2</sup> PERRY W. GRIGSBY, M.D.,<sup>1</sup> FAROQAH DUBASHI, M.D.,<sup>1</sup> TOM R. MILLER, M.D., Ph.D.,<sup>1</sup> PABLO ZARSKI, M.D.,<sup>1</sup> WALTER R. BOYCH, D.Sc.,<sup>1</sup> JACQUELINE ESTERMAN, Ph.D.,<sup>2</sup> AND DONALD A. LOW, Ph.D.,<sup>1</sup>  
<sup>1</sup>Department of Radiation Oncology and <sup>2</sup>Division of Nuclear Medicine, M.D. Anderson Institute of Radiation,  
Washington University School of Medicine, St. Louis, MO

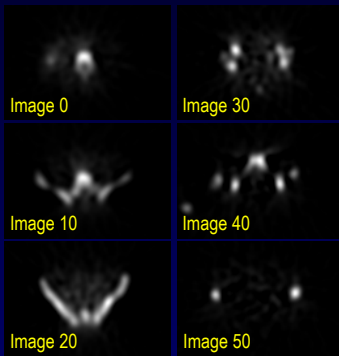


Fig. 1. Axial PET and CT image showing a positive PALN and kidneys.

PET/CT fusion for improving sensitivity (more complete definition of target volume)

## Tc-99m Bone Marrow Images

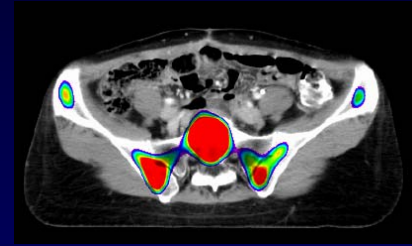
From J. Roeske, U of Chicago



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## SPECT-CT Image Fusion

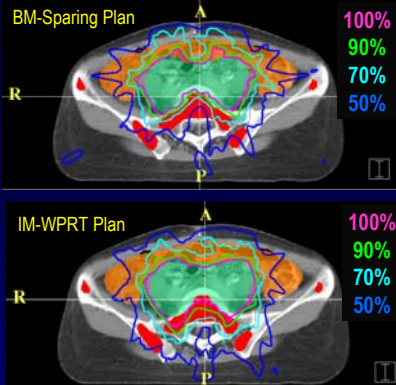


- Based on image fusion, highest intensity BM was contoured and used in planning process

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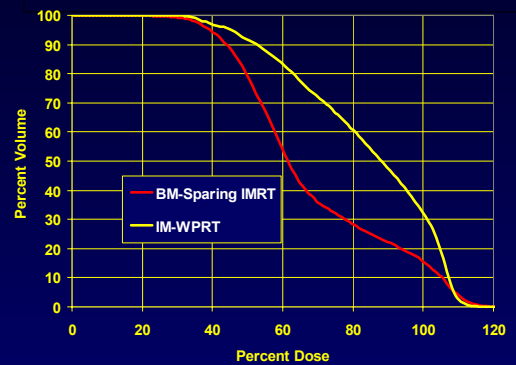
## Isodose Comparison – Upper Pelvis



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## Bone Marrow DVHs

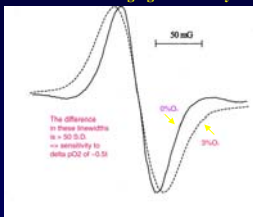


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## EPR Spectrum Response of Symmetric Trityl (deuterated) to Oxygen

NIH Research Resource for EPR Imaging in Vivo Physiology: H. Halpern

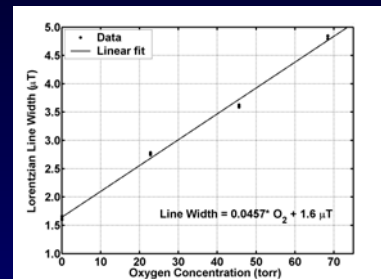


- No temp. dependence:  $< 0.05$  mG/K
- Low viscosity dependence  $\sim 1$  mG/cP
- Minimal self quenching

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## Line widths $pO_2$ calibration



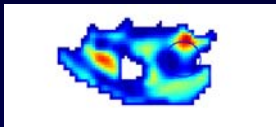
Oxygen dependence of spin packet width obtained in a series of homogenous solutions of OX31:  
Since minimal viscosity dependence, aqueous=tissue

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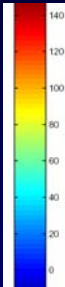
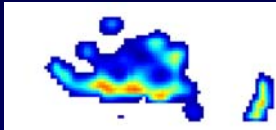
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## Oxygen Image of PC3 Xenograft Pre- and Post-Ad-EGR-TNF $\alpha$ + 20 Gy Radiation

3 hours  
Pre-



3 days  
Post



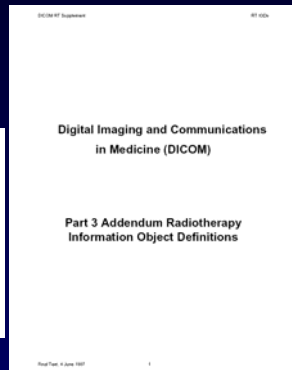
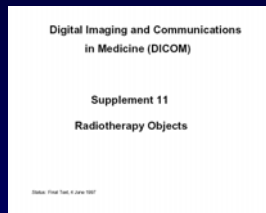
How do we get all these images?

DICOM – de-“Babelizing” image import.

Every clinically used modality does or will support DICOM transfer of images. All we need to do is make sure we are capable of accepting them.



DICOM-RT: support for communication of RT-specific non-image information



## DICOM basic concepts: information objects

An *Information Object* is "an abstraction of a real information entity (e.g., CT Image, Study, etc.) Which is acted upon by one or more DICOM Commands." An *Information Object Instance* is "a representation of an occurrence of a real-world entity, which includes values for the attributes of the Information Object Class to which the entity belongs" (e.g., a specific CT image).

"An *Information Object Definition* (IOD) is an object-oriented abstract data model used to specify information about Real-World Objects. An IOD provides communicating Application Entities with a common view of the information to be exchanged."

IODs are thus a common language by which different computers and programs may "read" and "write" images. IODs must exist for each type of image (or non-image) dataset which is to be communicated using DICOM. IODs are defined in the 2001 standard for CT, Computed Radiography (CR), Nuclear Medicine, MR, PET, US, Secondary Capture (SC, e.g. digitized film, screen dump), Overlay, Curve, X-ray Angiography, X-ray Radiography/Fluoroscopy, RT Image, RT Dose, RT Structure Set, RT Plan, Digital Mammography, Digital Oral X-ray, RT Beams Treatment Record, RT Brachy Treatment Record, Visible Light Image, Waveform and others.

## DICOM basic concepts – service and service object pair classes

A *Service Class* is "a structured description of a service which is supported by cooperating DICOM Application Entities using specific DICOM commands acting on a specific class of Information Object." Examples include storage, query, retrieval and print service classes.

A *Service-Object Pair (SOP) Class* is "the union of a specific set of ... Services and one related Information Object Definition (as specified by a Service Class Definition) which completely defines a precise context for communication." For example, CT Image (the object) Storage (the service) is a Service-Object Pair.

A *Service Class User (SCU)* is a client that utilizes a service

A *Service Class Provider (SCP)* is a server that offers a service

Your desktop PC when receiving images from your PACS system is a storage SCP, and the PACS is an SCU of your service.

**B.6 STANDARD SOP CLASSES**

The SOP Classes in the Storage Service Class identify the Composite IODs to be stored. Table B.6-1 identifies Standard SOP Classes.

SOP Class Name	SOP Class UID	IOD Specification (defined in PS 3.2)
Computed Radiography Image Storage	1.2.840.10008.5.1.4.1.1	
CT Image Storage	1.2.840.10008.5.1.4.1.2	
Hardcopy Color Image Storage	1.2.840.10008.5.1.1.30	
Hardcopy Grayscale Image Storage	1.2.840.10008.5.1.1.28	
MR Image Storage	1.2.840.10008.5.1.4.1.4	
Nuclear Medicine Image Storage	1.2.840.10008.5.1.4.1.1.20	
Positron Emission Tomography Image Storage	1.2.840.10008.5.1.4.1.1.128	
RT Dose Storage	1.2.840.10008.5.1.4.1.1.481.2	
RT Image Storage	1.2.840.10008.5.1.4.1.1.481.1	
RT Plan Storage	1.2.840.10008.5.1.4.1.1.481.5	
RT Structure Set Storage	1.2.840.10008.5.1.4.1.1.481.3	
RT Beams Treatment Record Storage	1.2.840.10008.5.1.4.1.1.481.4	
RT Brachy Treatment Record Storage	1.2.840.10008.5.1.4.1.1.481.6	
RT Treatment Summary Record Storage	1.2.840.10008.5.1.4.1.1.481.7	
Secondary Capture Image Storage	1.2.840.10008.5.1.4.1.1.7	

## DICOM basic concepts - conformance

PS 3.2 defines principles that implementations claiming conformance to the Standard shall follow. PS 3.2 specifies:

- the minimum general conformance requirements that must be met by any implementation claiming conformance to the DICOM Standard. Additional conformance requirements for particular features, Service Classes, Information Objects, and communications protocols may be found in the conformance sections of other Parts of the DICOM Standard.
- the purpose and structure of a Conformance Statement. PS 3.2 provides a framework by which conformance information can be placed into a Conformance Statement as dictated by the conformance sections of other Parts of the DICOM Standard.

The DICOM Standard does not specify:

- testing or validation procedures to assess an implementation's conformance to the Standard;
- testing or validation procedures to assess whether an implementation matches to its Conformance Statement;
- what optional features, Service Classes, or Information Objects should be supported for a given type of device.



DICOM File: 25262.110

DICOM Dump Elements

Object type: RLEImage LIST

Object size: 526998

Group: 0008, Length: 486

0008 0008 4 // ID Group Length// 1e6 486

0008 0005 10 // ID Specific Character Set//ISO\_IR 100

0008 0008 22 // ID Image Type//ORIGINALPRIMARYAXIAL

0008 0012 8 // ID Instance Creation Date//20030527

0008 0013 14 // ID Instance Creation Time//100000.000000

0008 0016 26 // ID SOP Class UID//1.2.840.10008.5.1.4.1.1.2 CT\_IMAGE\_STORAGE\_SOP\_CLASS\_UID

0008 0018 46 // ID SOP Instance UID//2.16.840.1.113662.2.12.0.3034.1054033892.1335

0008 0020 8 // ID Study Date//20030527

0008 0021 8 // ID Series Date//20030527

0008 0022 8 // ID Acquisition Date//20030527

0008 0030 14 // ID Study Time//061628.000000

0008 0031 14 // ID Series Time//095000.000000

0008 0032 14 // ID Acquisition Time//100022.000000

0008 0050 0 // ID Acquisition Number//

0008 0060 2 // ID Modality//CT

0008 0070 8 // ID Manufacturer//Marconi

0008 0080 22 // ID Institution Name//University of Chicago

0008 0081 20 // ID Institution Address//Institution Address

0008 0090 4 // ID Referring Physician's Name//JAN

0008 1010 2 // ID Station Name//R1

0008 1030 18 // ID Study Description//POST IMPLANT SCAN

0008 1040 20 // ID Institutional Department Name//radiation oncology

0008 1070 6 // ID Operator's Name//AC/MS

0008 1080 8 // ID Manufacturer Model Name//AcqSiacT

Group: 0010, Length: 58

0010 0000 4 // PAT Group Length// 3a 58

0010 0010 16 // PAT Patient Name//TEST

0010 0020 8 // PAT Patient ID//0263404

0010 0030 0 // PAT Patient Birthdate//

0010 0040 2 // PAT Patient Sex//M

Group: 0011, Length: 540

0011 0000 4 // Unknown group length// 21c 540

0011 0010 34 // //Unimplemented

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Types of information transmitted and stored by DICOM  
This is the info for a single CT slice

DICOM patient coordinate system  
all coordinates in millimeters

Y into page (posterior)

Z cranial

X to patient left

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Links to DICOM info and software for viewing, sending, receiving, ...

DICOM introduction and free software

<http://www.prodicology.net/magnum.es.uk/staff/11/thumbnails.html>

The DICOM Standard

This guide gives a brief description of the DICOM standard, which is commonly used for the transfer and storage of medical images.

- [An introduction to the DICOM single-file format](#)
- [The DICOM header](#)
- [DICOM image and sequence syntax \(a business and common\)](#)
- [DICOM image DICOM sequence](#)
- [DICOM image DICOM sequence](#)
- [DICOM image DICOM sequence](#)

An introduction to the DICOM single-file format

The Digital Imaging and Communications in Medicine (DICOM) standard was created by the National Electrical Manufacturers Association (NEMA) to aid the distribution and viewing of medical images, such as CT scans, MRIs, and ultrasound. Part 10 of the standard describes a file format for the distribution of images. This format is an extension of the older NEMA standard. Most people refer to image files which are compliant with Part 10 of the DICOM standard as DICOM format files. A complete copy of the standard in PDF format is available for [download](#) (details of the standard are organized by year).

A single DICOM file contains both a header (which stores information about the patient's name, the type of scan, image dimensions, etc.) as well as all of the image data (which can contain information in three dimensions). This is different from the popular Analyze format, which stores the image data in one file (1+ images) and the header data in another file (1 file). Another difference between DICOM and Analyze is that the DICOM image data can be compressed (interoperably) to reduce the storage size. Files can be compressed using lossy or lossless variants of the JPEG format, as well as a lossless Run-Length Encoding format (which is identical to the packed-bits compression found in some TIFF format images).

DICOM is the most common standard for receiving scans from a hospital. Neuroimagers and neurophysiologists who wish to use SPM to normalize scans to stereotaxic space will need to convert these files to Analyze format. My software [3DAnalyze](#) software will directly convert most DICOM images to and from Analyze format. Eric Niell's free [MedImage](#) and [NImage](#) software can also convert between Analyze and DICOM.

The DICOM header

The image on the left shows a hypothetical DICOM image file. In this example, the first 764 bytes

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Image Fusion  
and  
Multimodality 3D Imaging

Terminology

- **Multimodality imaging:**
  - the use of two or more imaging techniques (modalities) to provide information in a given diagnostic or research situation.
- **Image fusion, sensor fusion:**
  - the synthesis of two or more signals into a single dataset; also often used to describe the process of displaying such synthesized data.
- **Image registration, matching:**
  - the process by which one dataset is mapped onto another. Involves establishment of a coordinate transformation relating the native coordinate systems of the two datasets.

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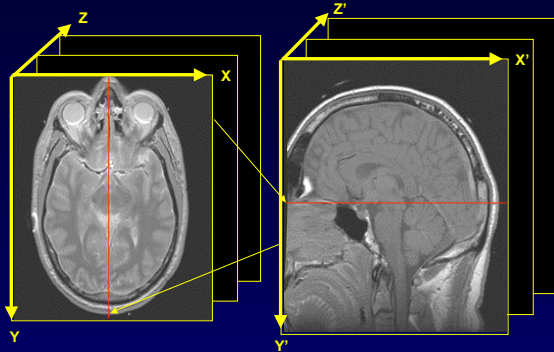
Registration:

**"...the determination of a one-to-one mapping between the coordinates in one space and those in another, such that points in the two spaces which correspond to the same anatomical point are mapped to each other."**

(C.R. Maurer and J.M. Fitzpatrick, "A Review of Medical Image Registration," in [Interactive Image Guided Neurosurgery](#), R.J. Maciunas ed., A.A.N.S., 1993.)

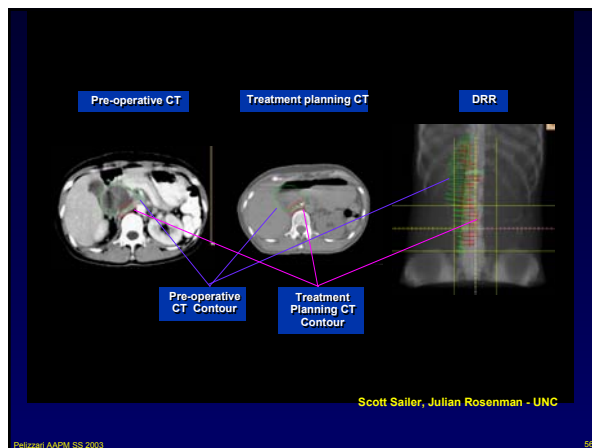
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Registration: find transformation between primed and unprimed coordinate systems such that corresponding anatomical points are mapped onto one another.



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Image source: NLM Visible Human Project



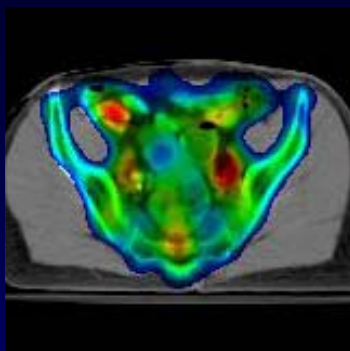
Scott Sailer, Julian Rosenman - UNC

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Merged CT and SPECT by surface matching of large blood vessels

RJ Hamilton, UC  
M Blend, UIC



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## Two Problems of Registration

- Register images to other images
  - Register images to the real world
- transfer image defined locations onto patient
- transfer locations from patient to image model

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## Types of Data to be Registered

Class	Anatomic	Functional
3D	CT, MRI, US Digitized surface / point	PET, SPECT, fMRI EEG, MEG
2D Projection	Diagnostic radiograph Computed radiograph RT megavoltage image	Planar Scintitgraph
Multiple Projection	Biplane radiograph Stereo, angio	

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## Classification of registration methods

- What is matched? (which anatomical features)
- How is it matched? (cost function, parameter variation procedure, automatic vs manual)
- What kind of transformations are allowed? (linear, nonlinear, global, local)

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## A posteriori recovery of coordinate transformation

(Use information present in images to solve for required coordinate transformation)

Prospective - impose coordinate system on patient

Stereotactic frame

- rigidly fixed
- on mask

Applied fiducial marks

- on patient
- on mask

## A posteriori recovery of coordinate transformation

Retrospective - attempt to use patient-intrinsic info

### Feature based

Point landmarks in 3D

Curves, points on 2D projection images

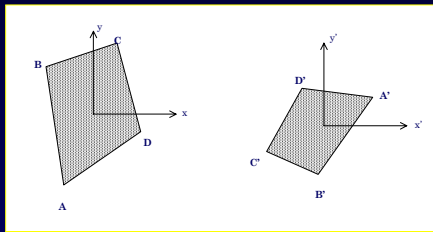
3D shape properties

- surfaces / volumes
- cores (= shape descriptors of objects)
- spatial moments
- of features

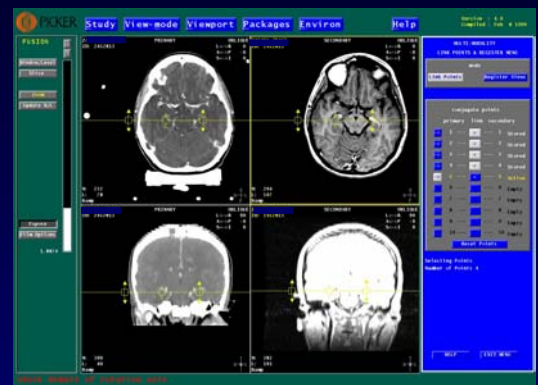
### Dense field (voxel) based

- intensity distribution, texture

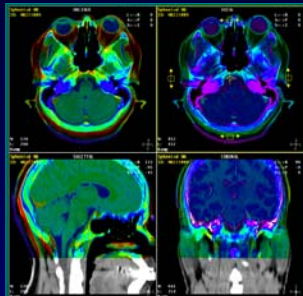
## Point matching: Procrustes method



## Point to point registration - AcQSim



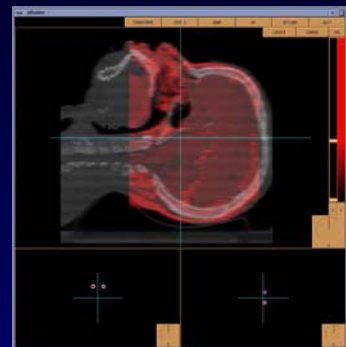
## Multi-Modality Interactive



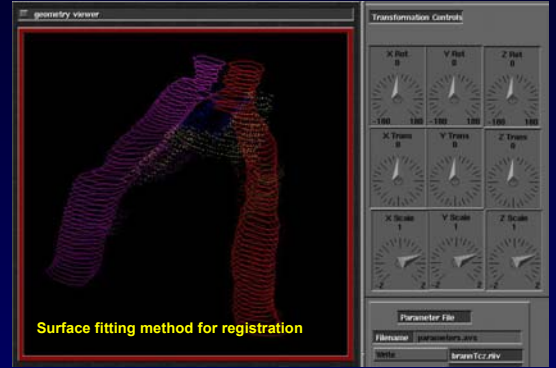
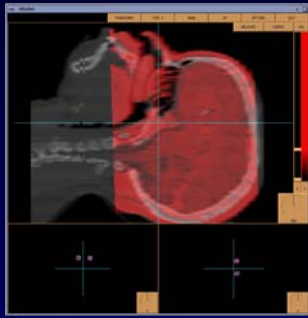
- Secondary study, shown as a colorwash overlay, is rotated and panned to match the primary CT simulation study

Slide: Marconi / Picker

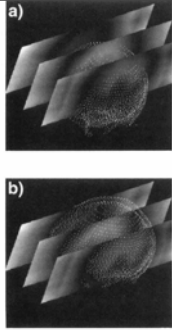
## PlanUNC "Xfusion" interactive image registration tool



## Xfusion: Images manually overlayed



## Surface fitting method for registration



## Automatic three-dimensional correlation of CT-CT, CT-MRI, and CT-SPECT using chamfer matching

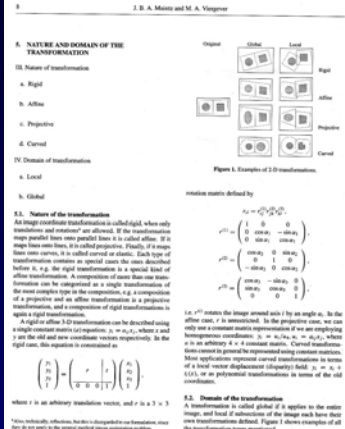
Margot van Hecke<sup>1</sup> and Hiram M. Kioy  
<sup>1</sup>Joint Center for Radiation Therapy, Department of Radiation Oncology, Harvard Medical School, Boston, Massachusetts 02128

(Received 15 June 1995; accepted for publication 15 April 1996)

### Chamfer matching:

- 1) compute distance transform from chosen feature (surface of skull, e.g.) in one volume
- 2) position corresponding object from second volume so sum of distance transform at all points is minimum ->
- 3) Mean distance from second surface to first surface is minimized.

Fig. 4. Principle of 3D chamfer matching. (a) The distance transform of a feature (the skull) to the first volume is overlaid by contour points of the corresponding feature in the second volume. The pixel intensity indicates the distance from the feature to the first volume. In this 3D view, the 3D distance transform is visualized by three separate slices. The dark spots in the distance transform inside the skull are caused by the non-rigid frame which has not been removed from the template image. (b) A global optimization procedure is used which minimizes the average pixel value in the distance transform image under the points by translating, rotating and scaling all contour points. As a result, the set of contour points towards the distance transform area in the distance transform and template volume aligns.



## Consistent Image Registration

G. E. Christensen\* and H. J. Johnson



Fig. 1. Consistent image registration is based on the principle that the mappings  $h$  from  $T$  to  $S$  and  $g$  from  $S$  to  $T$  define a point by point correspondence between  $T$  and  $S$  that are consistent with each other. This consistency is enforced mathematically by jointly estimating  $h$  and  $g$  while constraining  $h$  and  $g$  to be inverse mappings of one another.

### E. Transformation Parameterization

A 3-D Fourier series representation [17] is used to parameterize the forward and reverse transformations. This parameterization is simpler than the parameterizations used in our previous work [14], [28], [29] and each basis coefficient can be interpreted as the weight of a harmonic component in a single coordinate direction. Let  $k = [k_1, k_2, k_3]$  and  $n = [n_1, n_2, n_3]$ . The displacement fields are defined to have the form

$$u_k(x) = \sum_{k \in \Omega_d} \mu[k] e^{i(x \cdot Nk/4)} \quad (6)$$

and

$$w_k(x) = \sum_{k \in \Omega_d} \eta[k] e^{i(x \cdot Nk/4)}$$

Image similarity constraint

Cost function

$$C(\mu, \eta, r) = \frac{1}{\sigma^2 N_1 N_2 N_3} \sum_{n \in \Omega_d} [T_d[Nn/4, r]] - S_d[n/2, r]]^2 + [S_d[Nn/4, r]] - T_d[n/2, r]]^2 + \chi \frac{1}{N_1 N_2 N_3} \sum_{k \in \Omega_d} \cdot \|u_k[n, r] - u_k[n, r]\|^2 + \|w_k[n, r] - u_k[n, r]\|^2 + \rho \sum_{k \in \Omega_d} \mu[k] D^2[k] |k| + \eta^2 |k| D^2[k] |k|. \quad (12)$$

Inverse consistency  $u \leftrightarrow w$

Elastic deformation energy - keeps displacement field relatively smooth

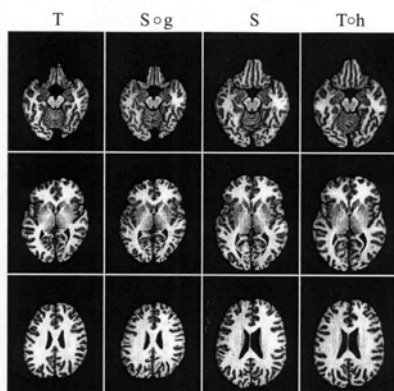


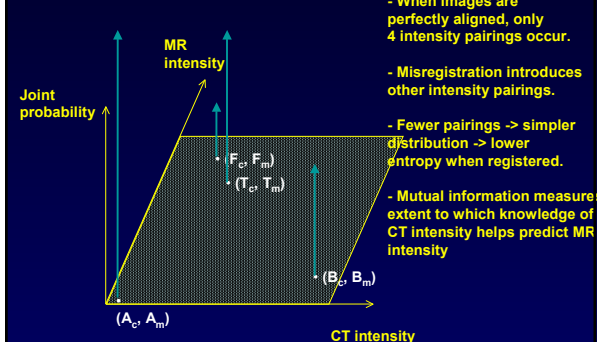
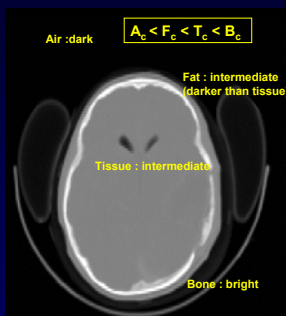
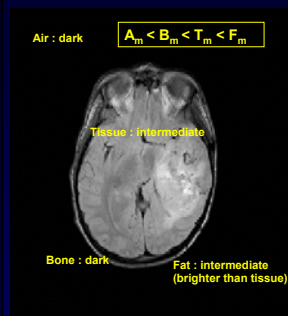
Fig. 6. Transverse slices 109, 135, and 165 (rows top to bottom) from the full resolution MRI-to-MRI registration experiment. The columns from left to right correspond to the template  $T$ , the deformed target  $S \circ g$ , the target  $S$  and the deformed template  $T \circ h$ . The intensities are on a range from 0 to 1.0.

### Pixel by pixel registration: maximization of mutual information

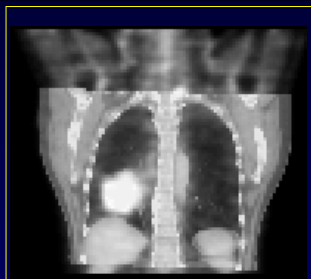
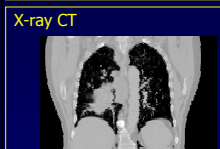
**Principle:** although anatomical regions may appear with different relative intensities in different modalities, these intensities are highly correlated.

**Joint probability distribution** when correctly registered is highly peaked; when misregistered, spread out. Peaked vs spread out nature is expressed formally in terms of entropy of the distribution.

**Mutual information** expresses the degree to which one image's intensities can be predicted given knowledge of the other - similar to correlation but more informative.



### PET-CT Registration: hybrid landmark / MI method



**PET – CT Fusion**

### Assessment of accuracy

**Problem with any method:** how to get a case specific estimate of accuracy

**Typical solution:** visual evaluation

- reformatted images
- side by side / linked cursor
- merge two data sets
- transformed VOIs

Not quantitative but intuitively satisfying  
Note requirement to manually verify 3 points when using FDA-cleared systems



