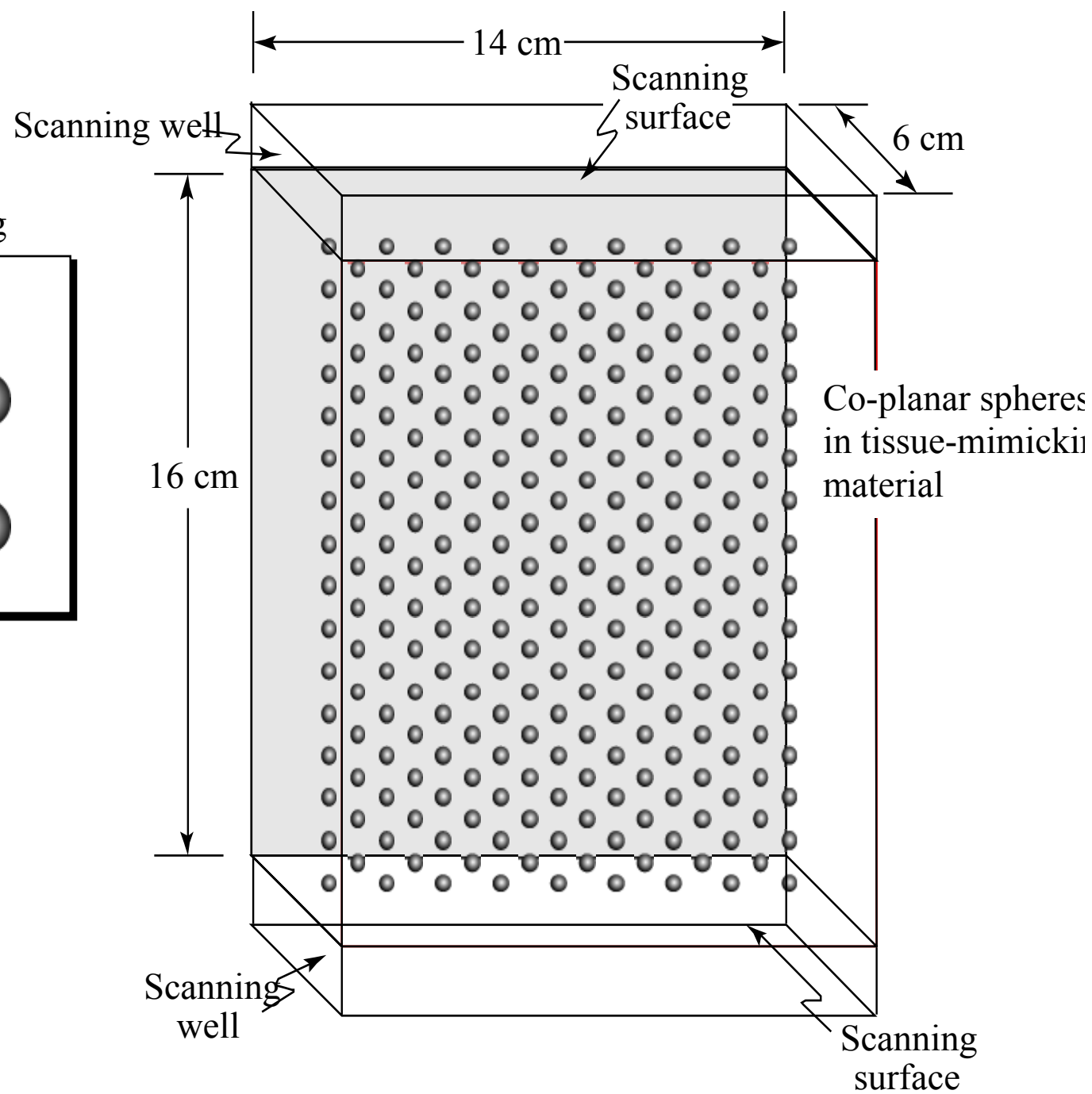
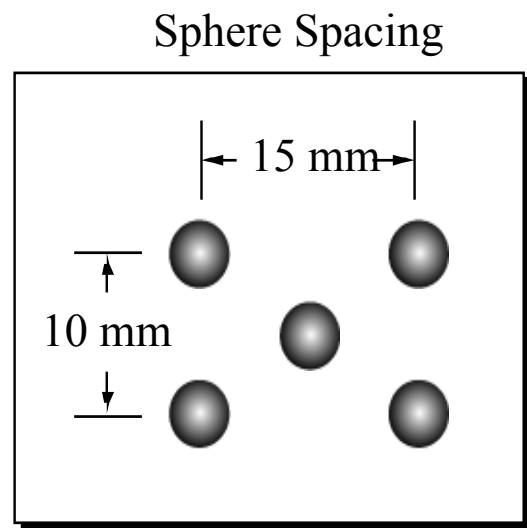


Clinically Relevant Phantom/automated System for Testing Ultrasound Imaging Performance

**by EL Madsen, JM Kofler,
MJ Lindstrom and F Kelcz**

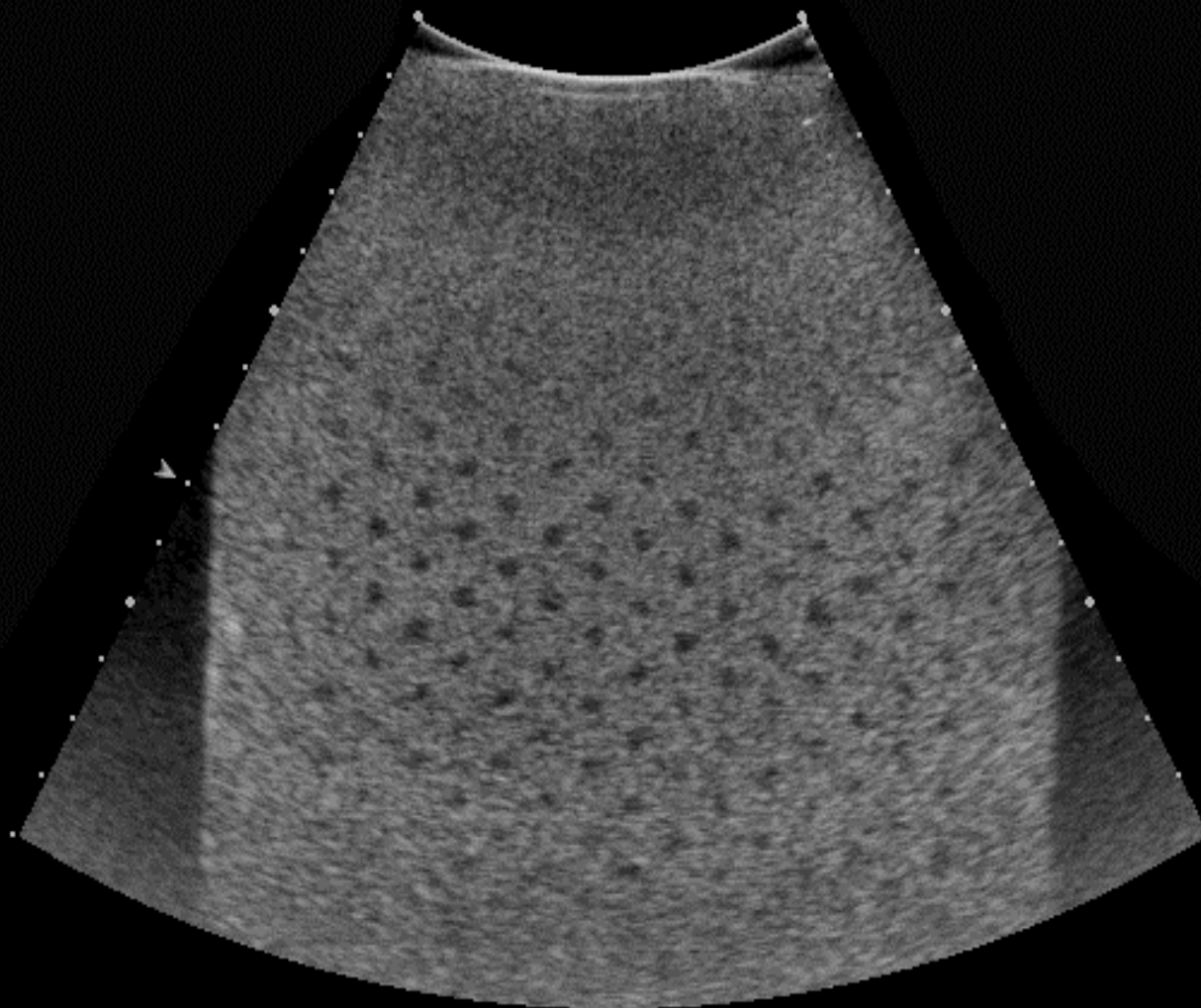
SUBJECTS:

- spherical lesion phantoms
- automated method for detecting lesions
- detection threshold *via* human observer correspondence
- clinical relevance of phantom/automation performance method *via* comparison with clinical performance on thyroid nodules

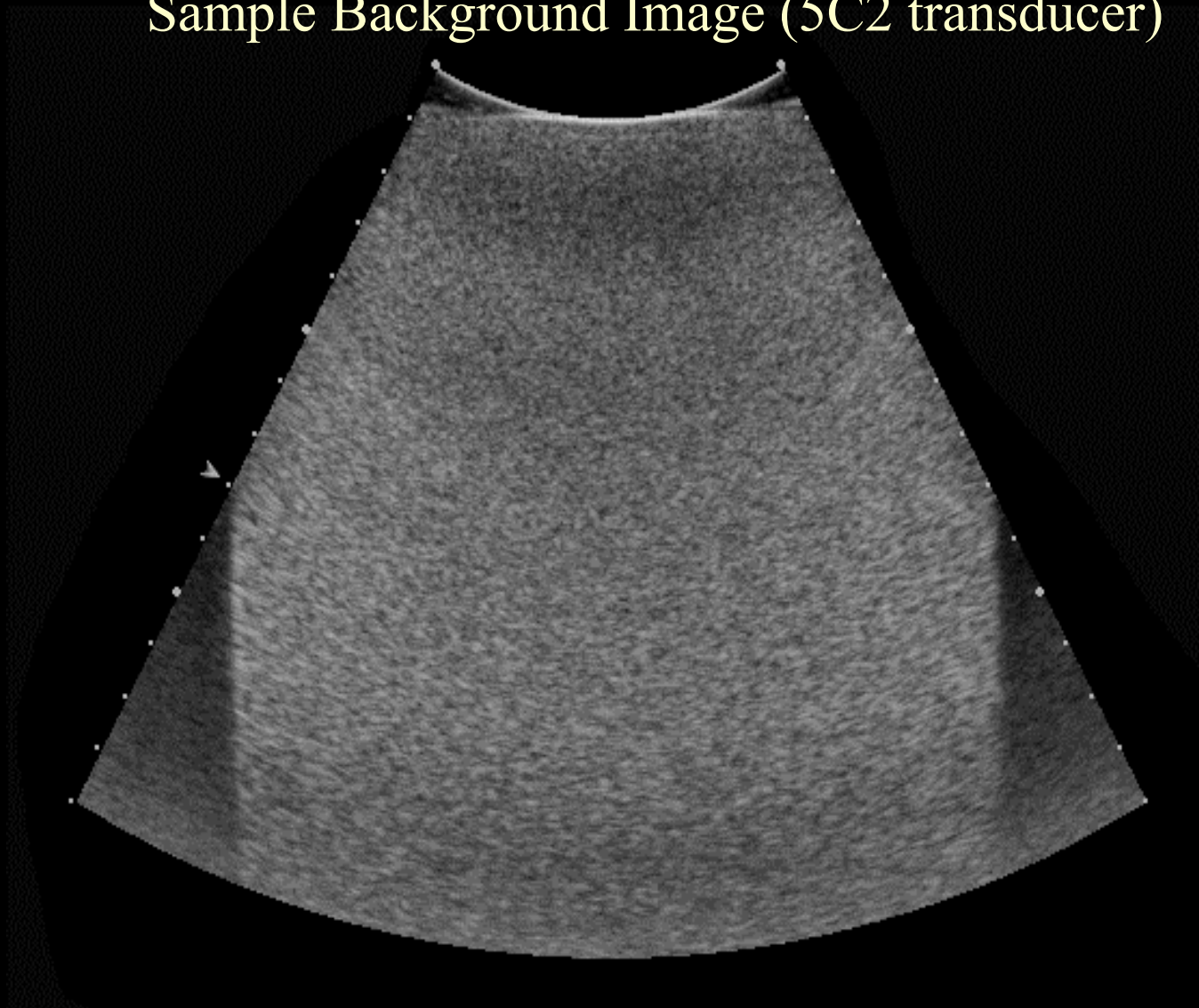


Alignment of scan plane on spheres employed a micrometer-driven rotation/translation device attached to the phantom top and holding the scan head.

4mm, -14 dB Spheres (5C2 transducer)



Sample Background Image (5C2 transducer)

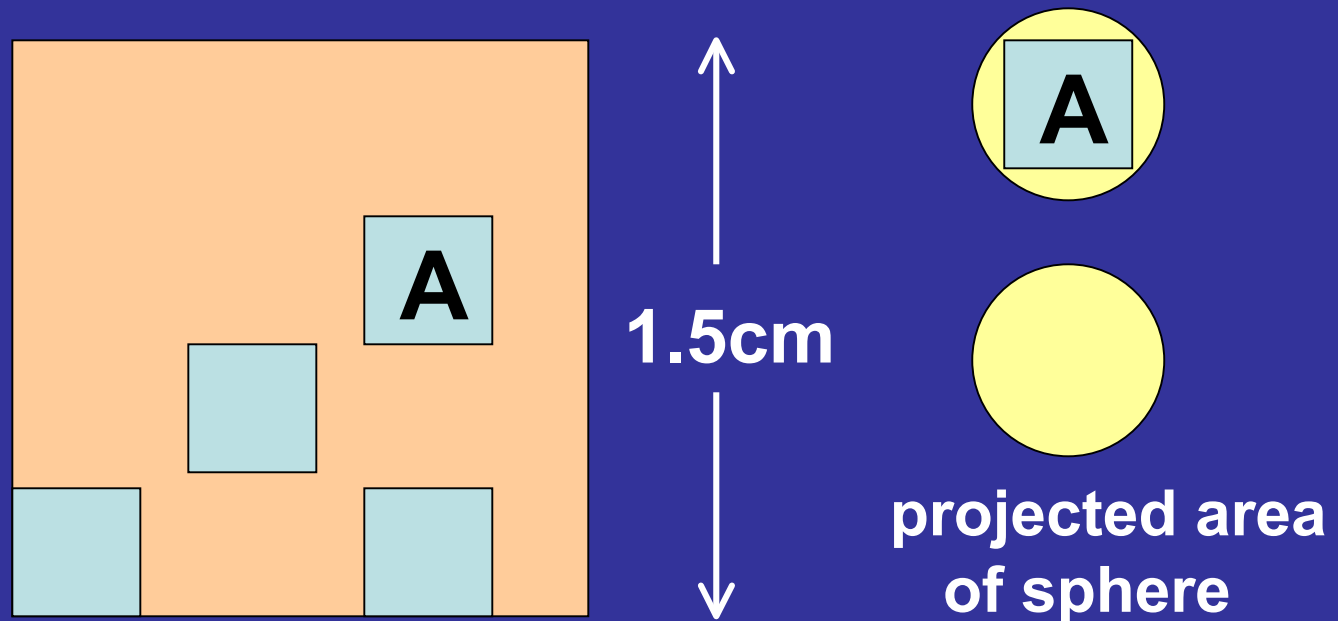


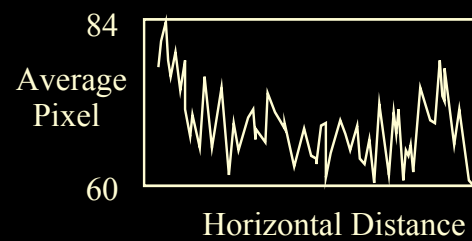
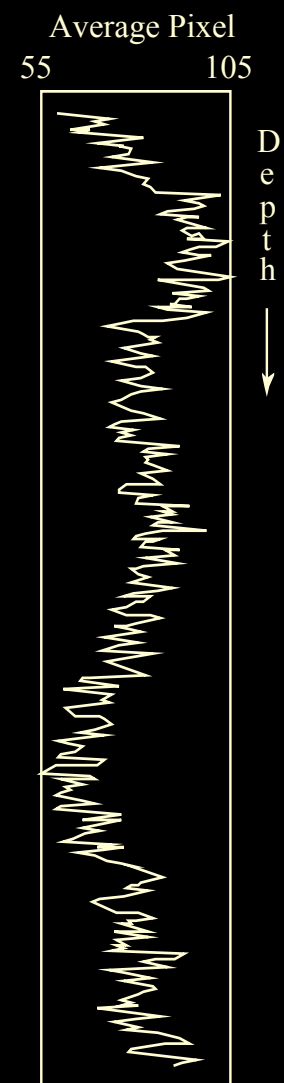
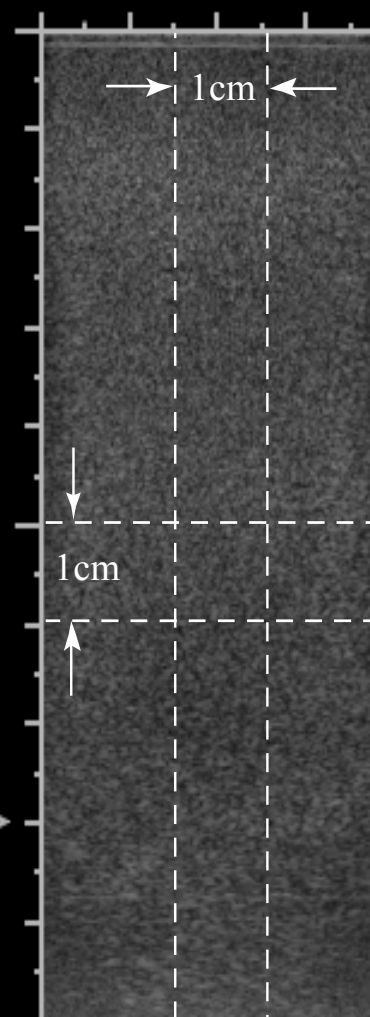
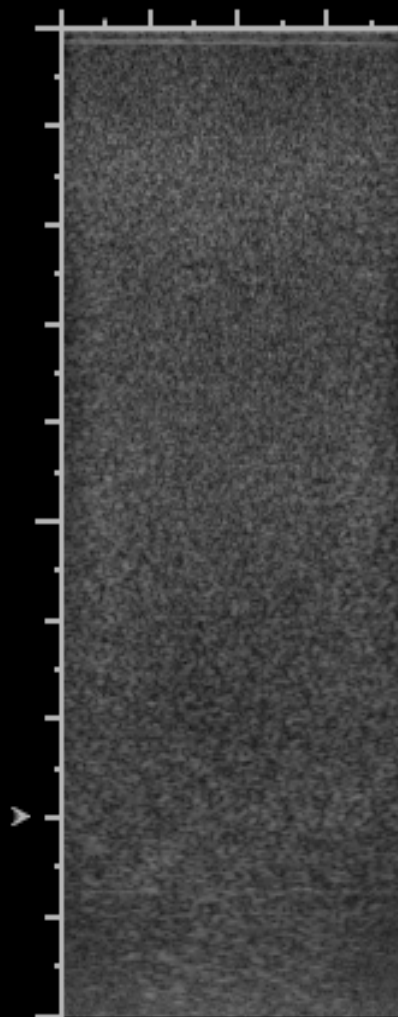
$$\overline{\text{LSNR}}_{\text{SD}} \approx \frac{\overline{S_L - S_B}}{\sigma_B}$$

$S_L \equiv$ mean pixel value over area A which is centered on the lesion and approximates the projected area of the target lesion

$S_B \equiv$ mean pixel value over a 1.5cmx1.5cm area centered at the lesion and excluding the area A

$\sigma_B \equiv$ standard deviation of mean pixel values over areas A distributed over a 1.5cmx1.5cm area of background image centered at the lesion position

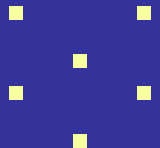




$$\overline{\text{LSNR}}_{\text{GCSD}} \approx \frac{\overline{S_L - S_B}}{\sigma_{\text{B,GC}}}$$

$\sigma_{\text{B,GC}} \equiv$ **gradient-corrected
standard deviation
relative to a plane fitted
to local mean pixel values**

DETERMINATION OF TARGET POSITIONS

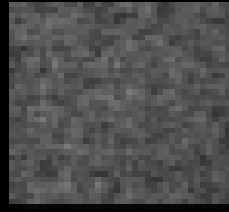
1. using the target image, *ad hoc* LSNR values are computed at relative array positions  and values summed
2. step 1 is repeated for a set of small translations and rotations
3. the most negative sum corresponds to alignment

RELATION OF AUTOMATED TO HUMAN OBSERVER DETECTABILITY

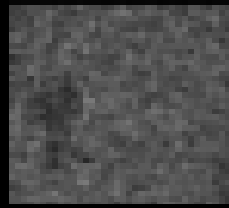
Two-Alternative Forced Choice (TAFC)

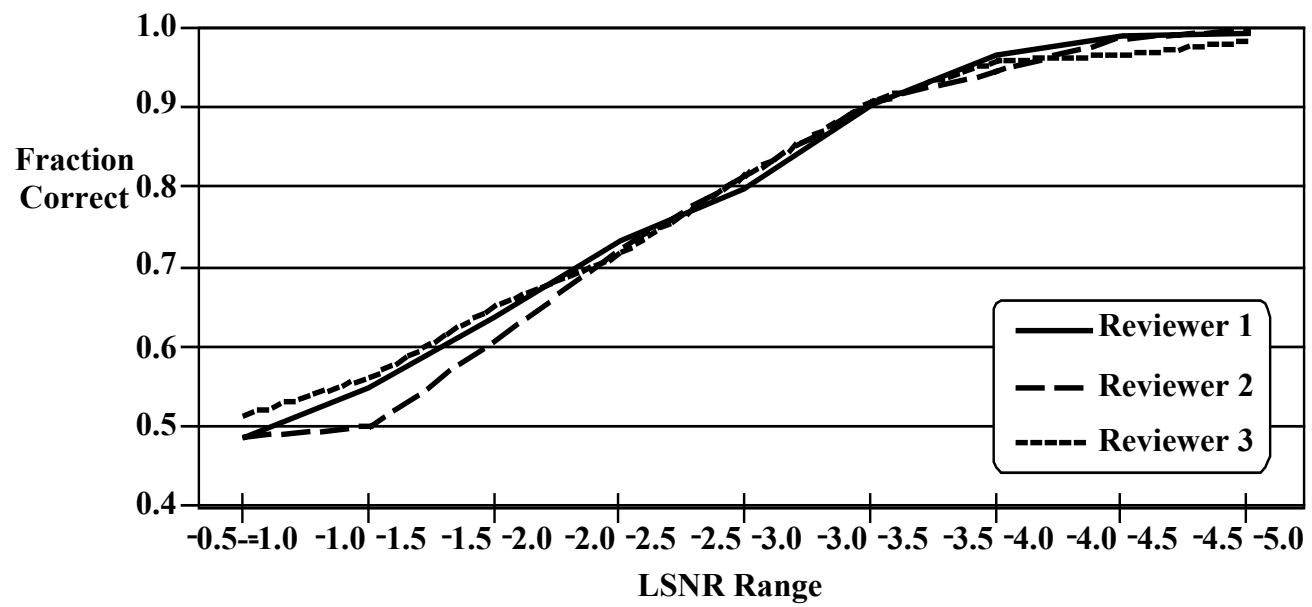
- 2, 3, 4 and 5 mm diameter spheres
- Contrasts -3, -6, -9 and -14 dB
- Acuson 128 scanner with:
 - 4 MHz sector (4V1);
 - 5 MHz curved array (5C2);
 - 6 MHz linear array (6L3)

- 5,646 pairs of 1cmx1cm image areas, one containing a lesion with LSNR between 1 and 6 and the other from a background image
- Lesion image on left or right (random)
- 3 human observers *required* to choose image which contains the lesion \equiv Two-Alternative Forced Choice (TAFC)

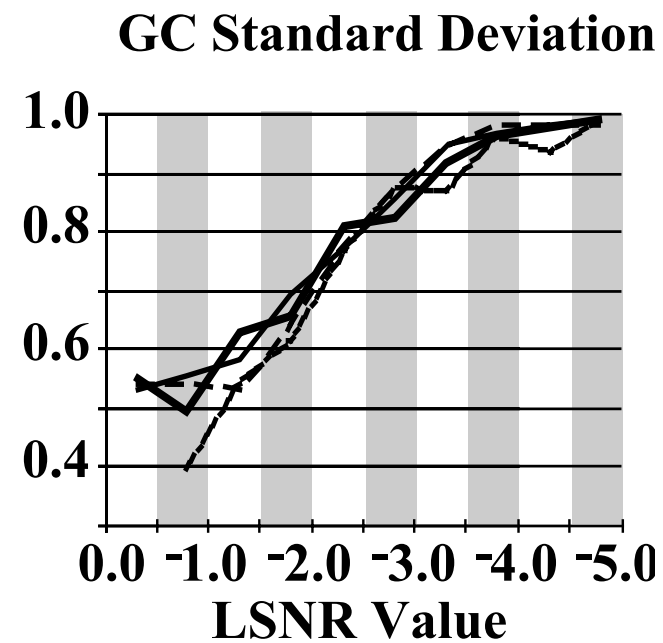
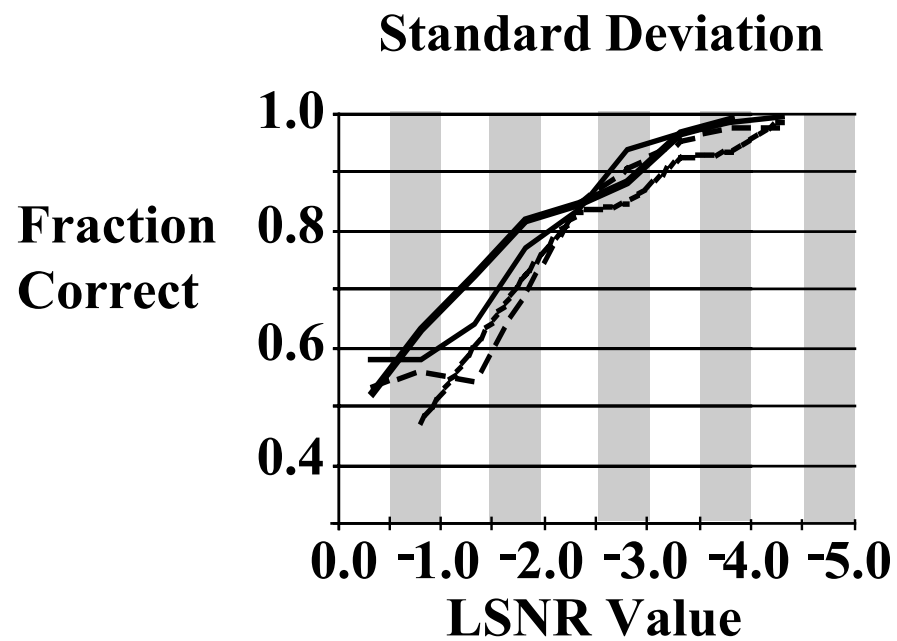


140066
3.0 mm spheres



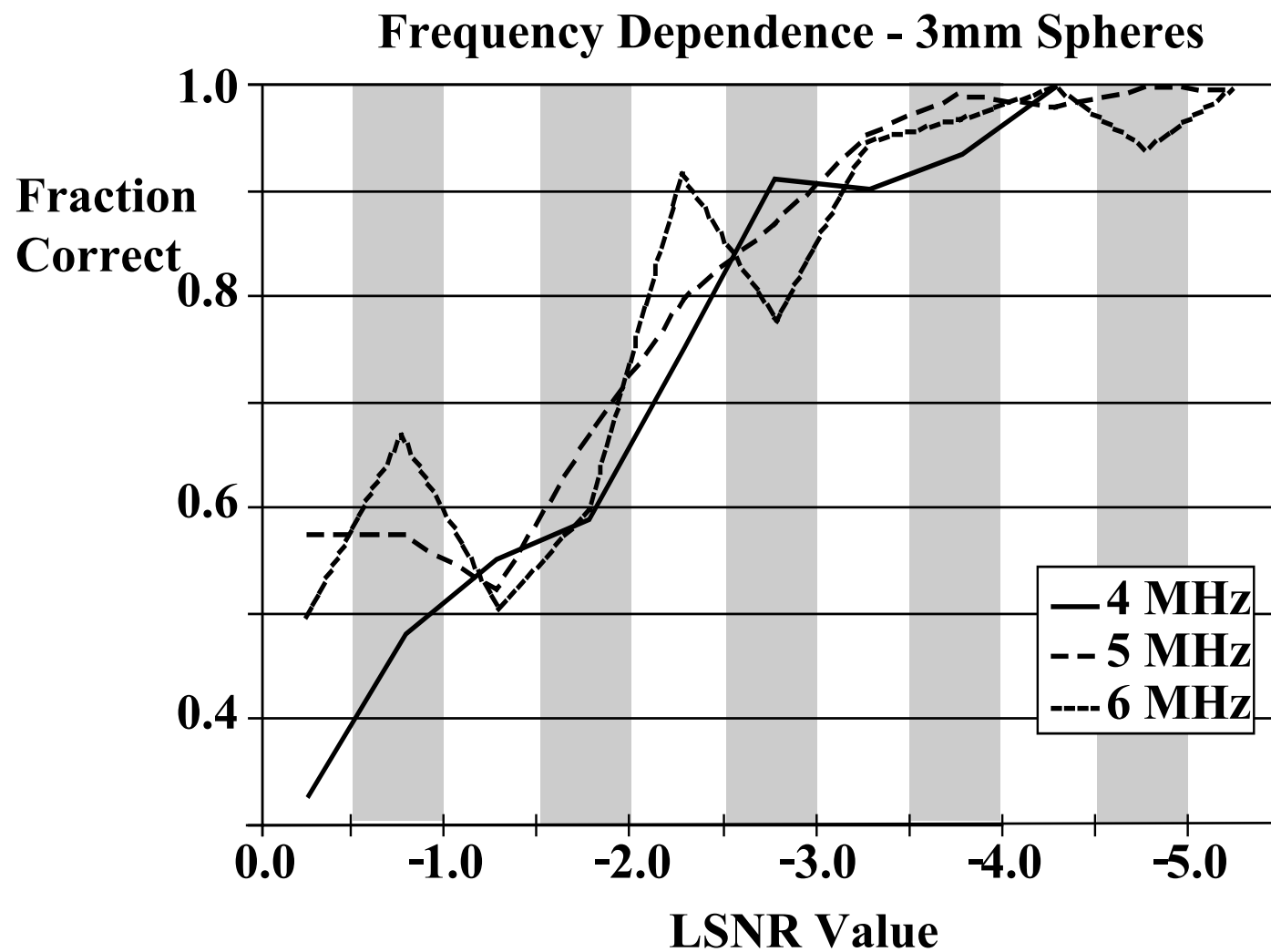


Legend: Sphere Diameter
..... 2 mm --- 3 mm — 4 mm — 5 mm

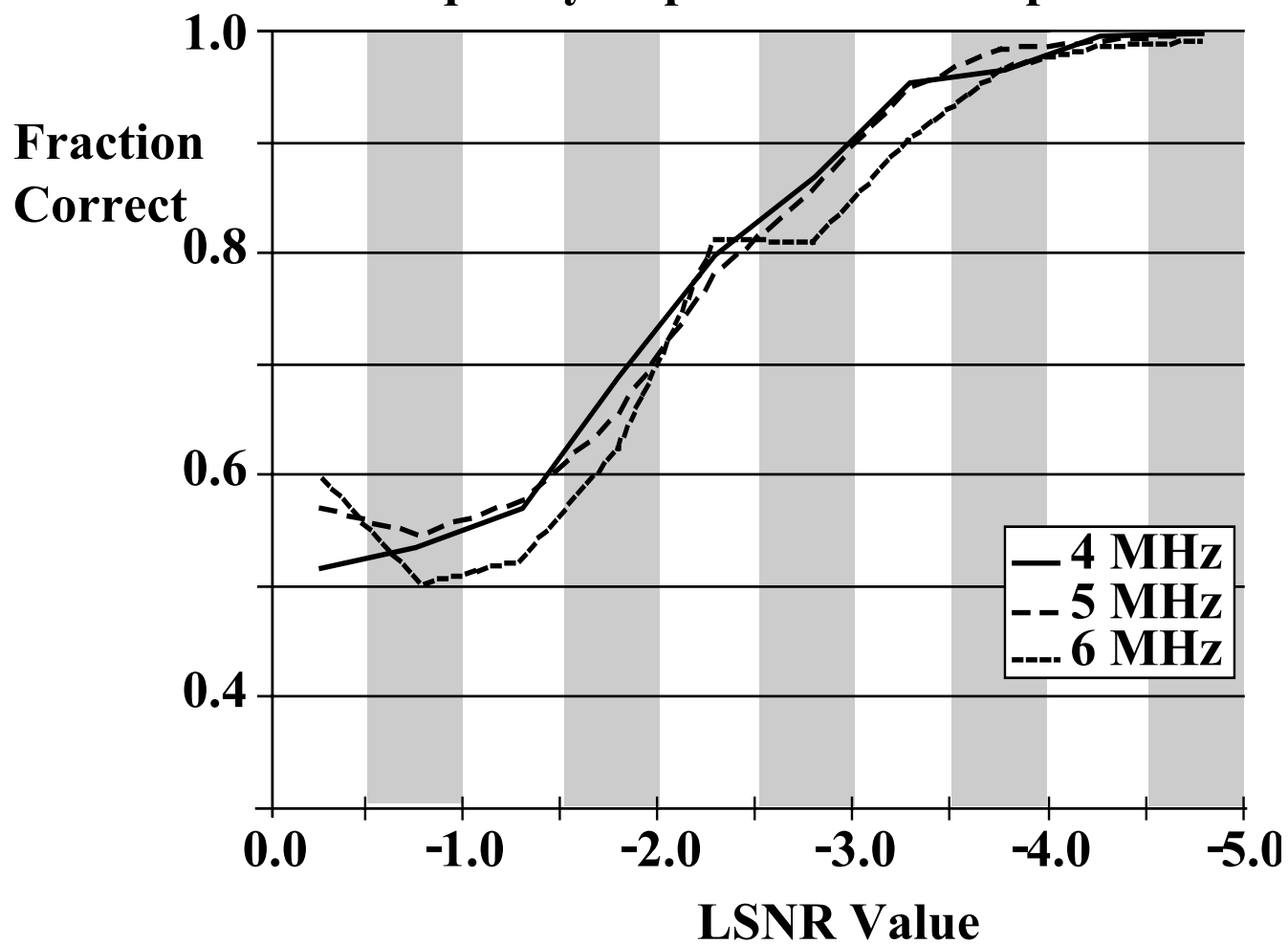


**Gradient-corrected standard deviation
for LSNR is more independent of lesion size**

**Thus, choose GCSD over ordinary standard
deviation method**



Frequency Dependence - All Sphere Sizes



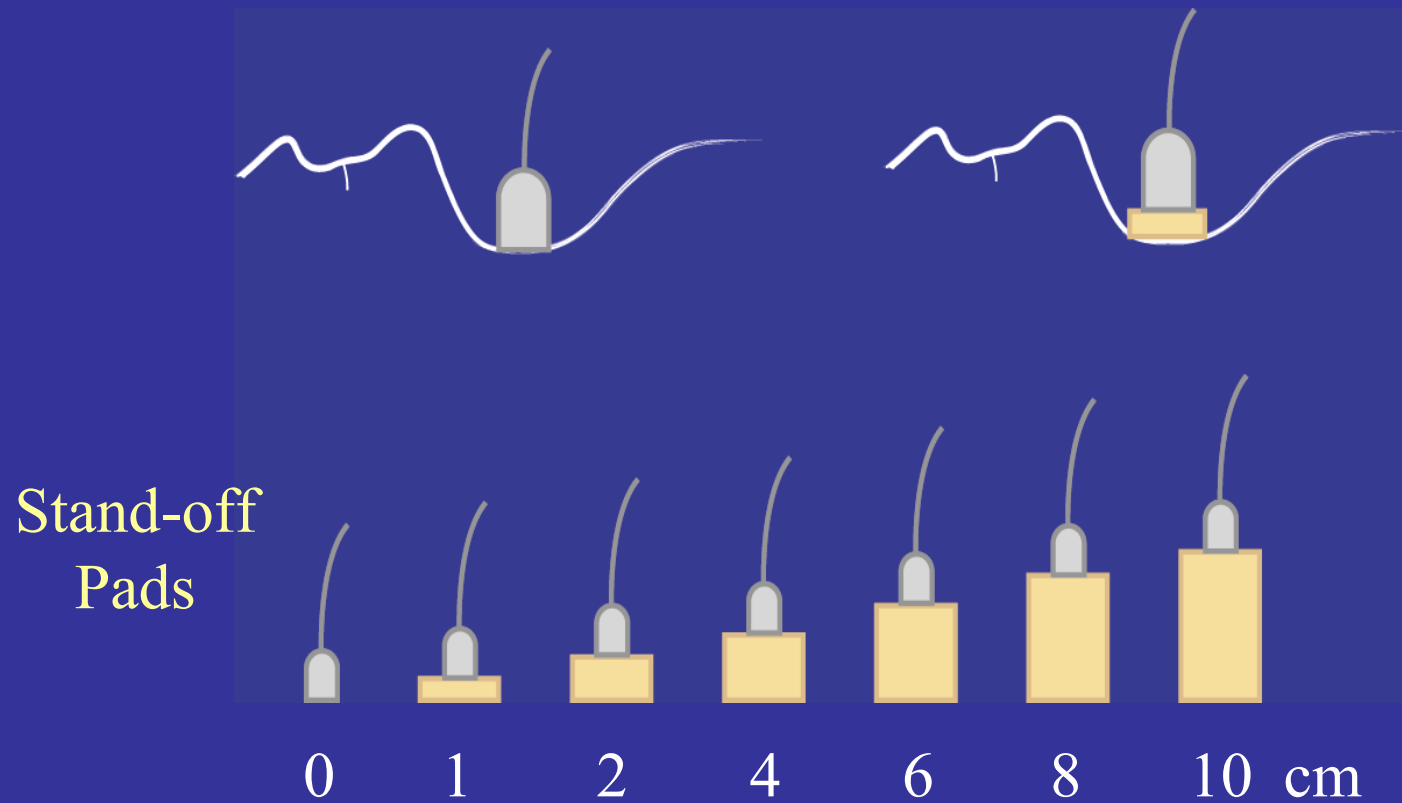
Selection of threshold somewhat subjective

- fraction correct of 0.7 on TAFC curve is a reasonable detectability threshold**
- corresponds to an LSNR value of -2**

STATISTICAL CONSIDERATIONS

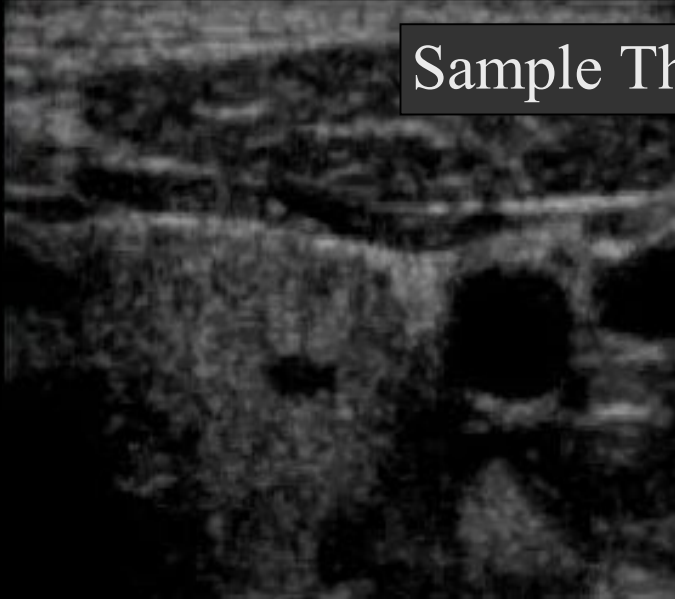
- More than one independent realization of LSNR value needed at a given depth
- Average of 8 realizations \Rightarrow standard error in LSNR of $\pm 0.3 \Leftrightarrow$ standard error $\approx \pm 0.05$ in TAFC fraction correct

Clinical Study-Thyroid Nodules: Methods

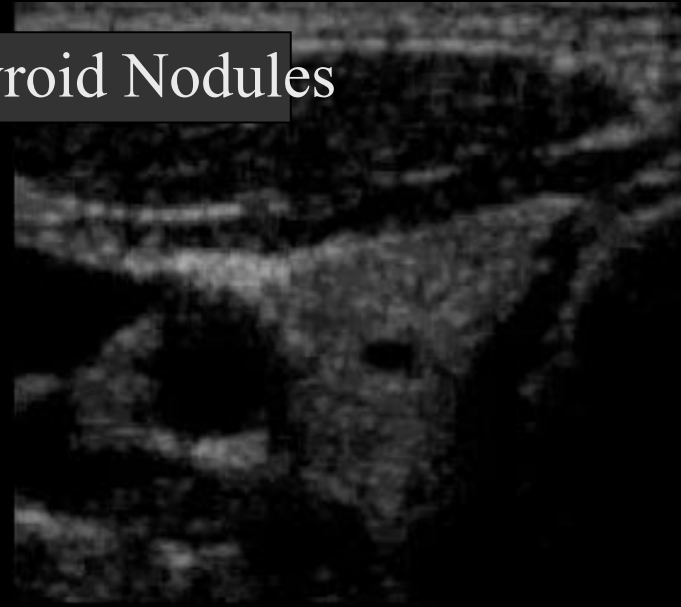


Sample Thyroid Nodules

A



B

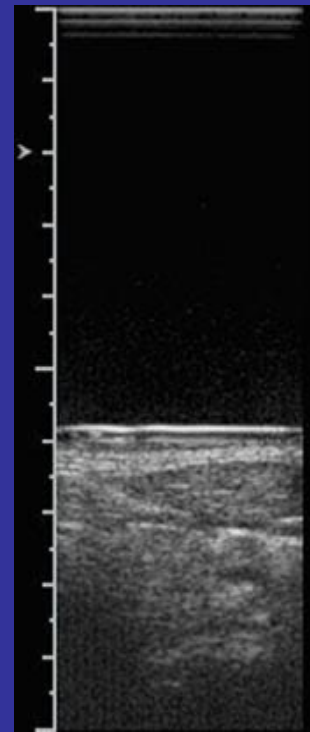
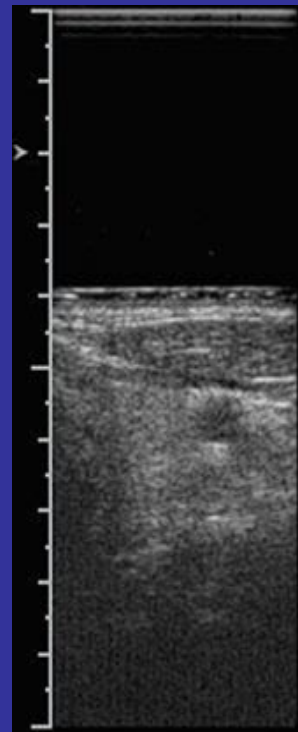
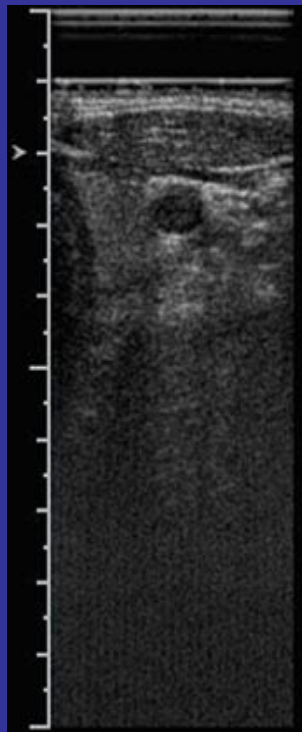
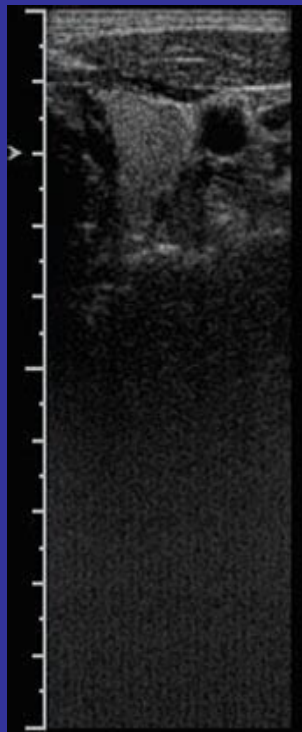
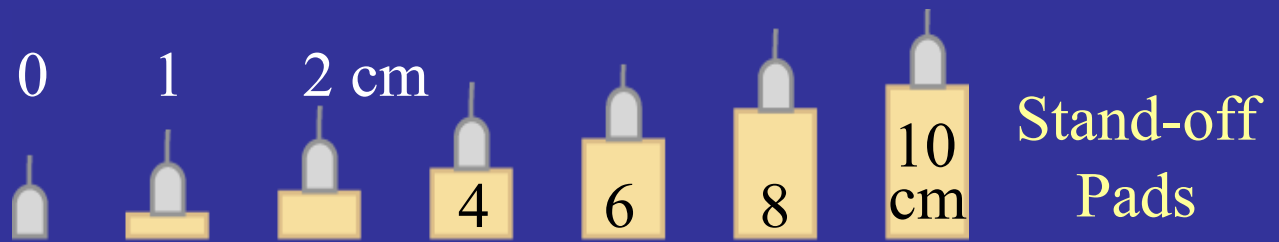


C



D





- 1. Acquire patient scans using a range of scan parameters**
 - **Scored by radiologists**
- 2. Acquire phantom scans using identical scan parameters**
 - **“Scored” by software**
- 3. Compare scores of radiologists and phantoms**

Scan Parameters

3 Transducers*

- 6L3 (6 MHz), 5C2 (5 MHz), 4V1 (4 MHz)
- 2 different focal depths each (2cm, 8cm)
- Other parameters constant

“Scan Configuration”: Transducer/Focal Zone Combination

* Acuson (Mountain View, CA)

Patient Scans

IMAGING

- 4 thyroid nodules
- Various depths
- Recorded 6 second cine loops
 - Masked and coded
 - Single movie (each scan configuration)
 - Reference sample (best clip of all)

REVIEW

- 9 Radiologists
- Score 1 (not detectable) to 5 (best)

Phantom Scans

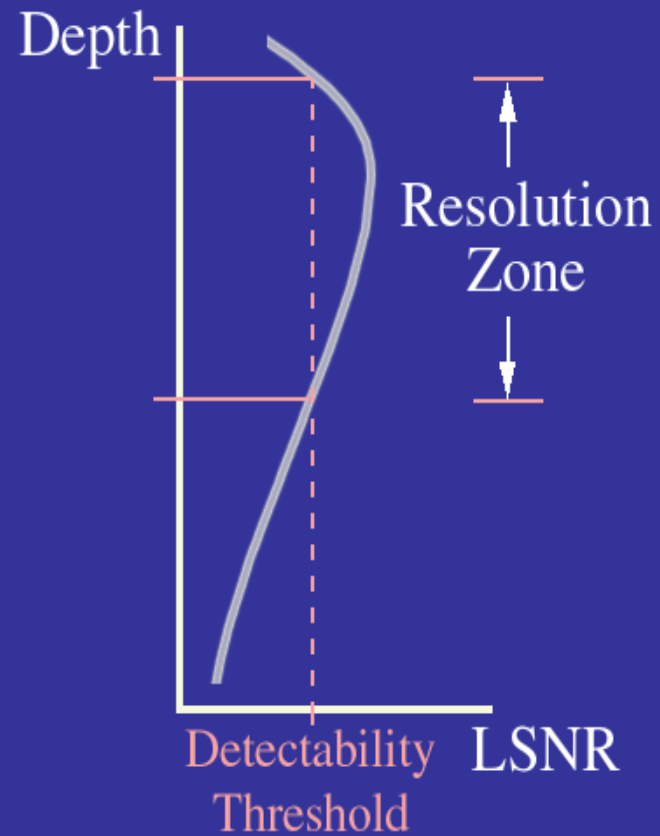
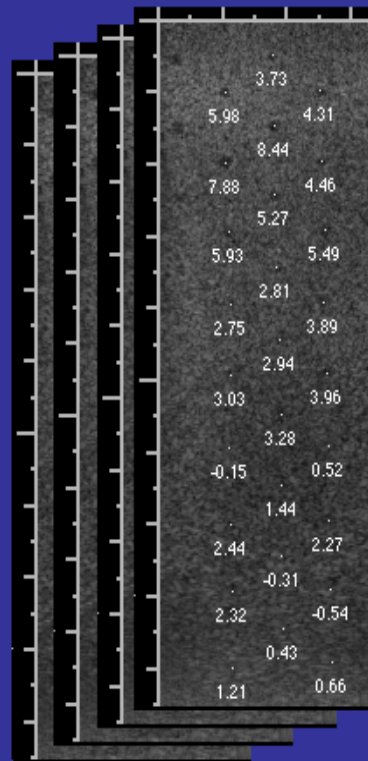
IMAGING

- 7 unique spherical lesion phantoms
 - 2mm @ -14 dB; 3mm @ -6, -9, -14 dB;
 - 4mm @ -9, -14 dB; 5mm @ -9 dB
- at least 8 independent realizations for each sphere size, contrast and depth interval

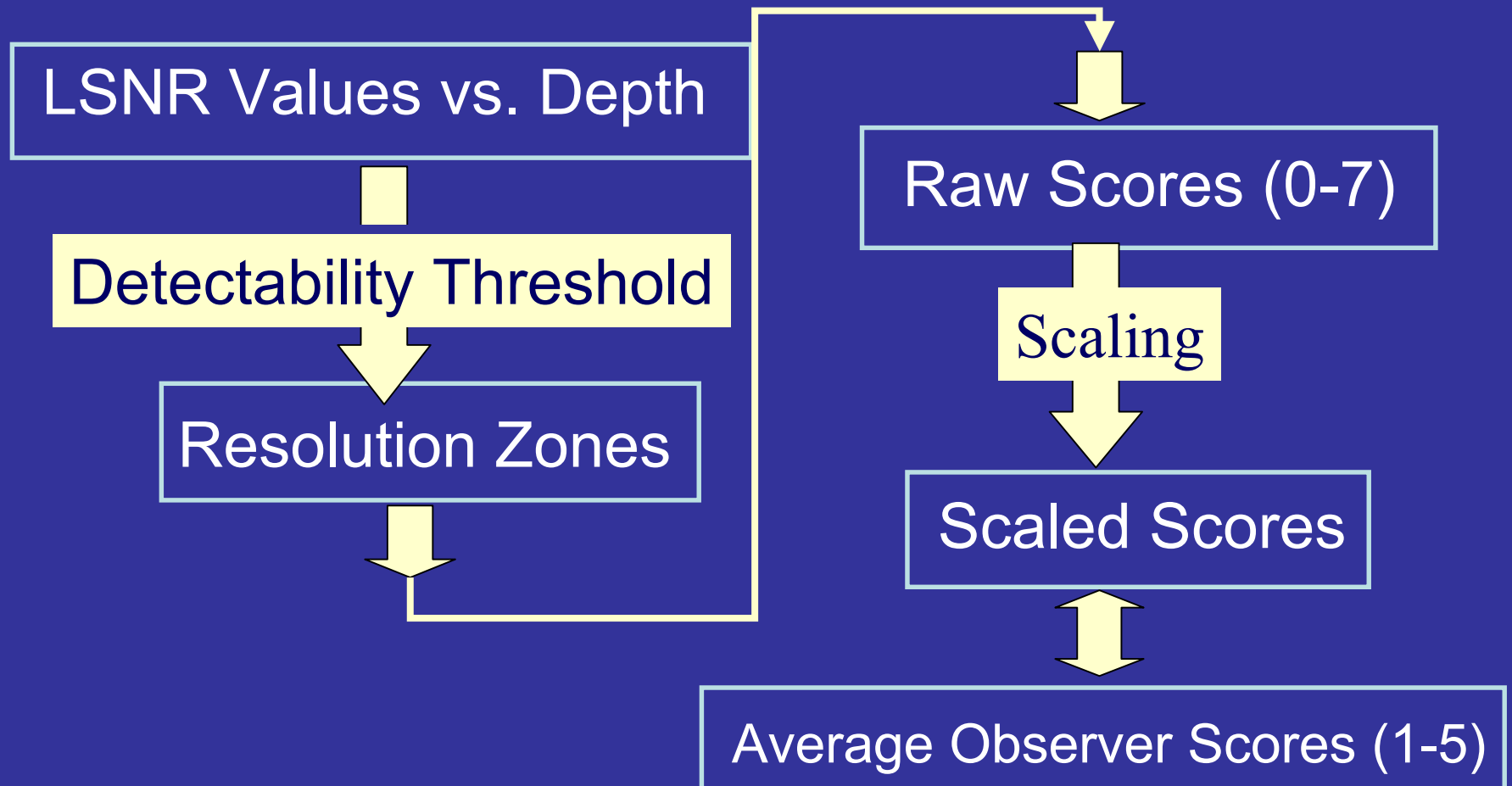
REVIEW

- Automated lesion signal-to-noise ratio (LSNR)
- Score from “resolution zone”

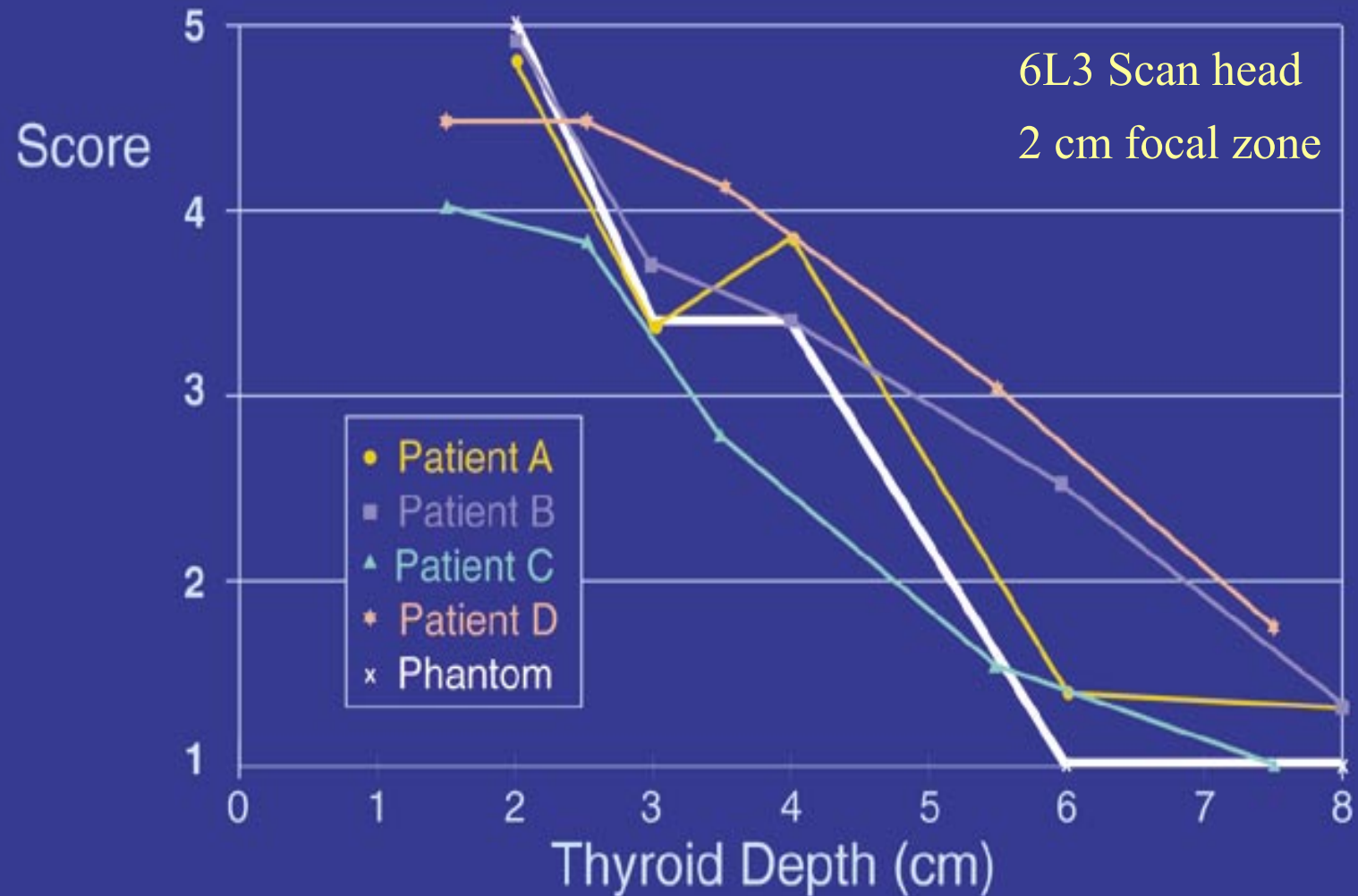
Resolution Zone



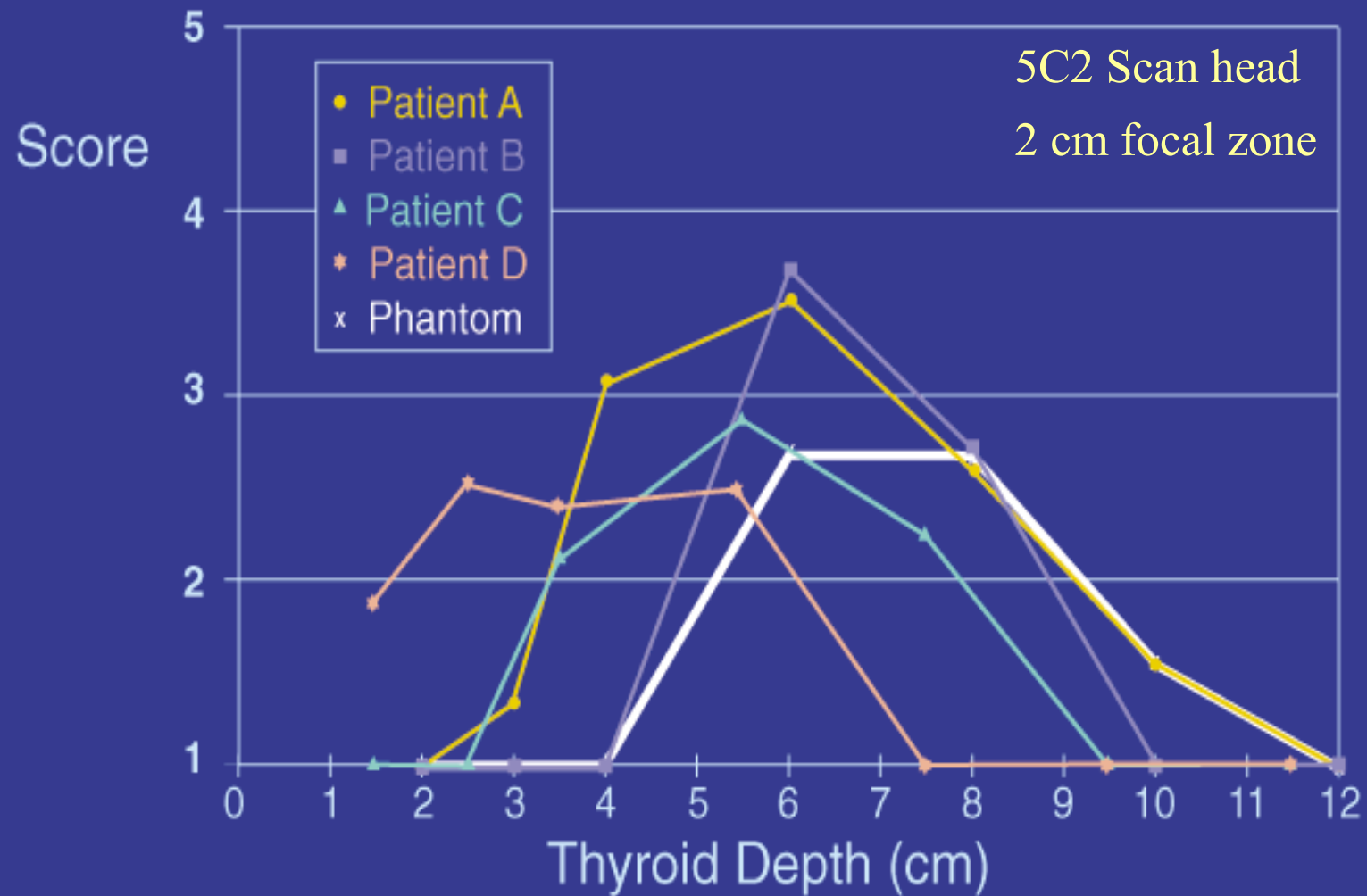
Results: Analysis Review



Thyroid Study: Some Results



Thyroid Study: Some Results



Kappa Coefficient

A statistical measure of agreement between two sets of data which suppresses biasing due to chance agreement.

<u>Kappa Value</u>	<u>Interpretation*</u>
Below 0.00	Poor agreement
0.00-0.20	Slight
0.21-0.40	Fair
0.41-0.60	Moderate
0.61-0.80	Substantial
0.81-1.00	Almost Perfect

Landis, J. & Koch, G. G. (1977). The measurement of observer agreement for categorical data
Biometrics, (33), 159-174.

$$\text{KAPPA COEFFICIENT} \equiv K \equiv \frac{p_o - p_e}{1 - p_e}$$

$$p_o \equiv \sum_{i,j}^n p_{ij} w_{ij} \quad p_o \equiv \sum_{i,j}^n p_{i \cdot} p_{\cdot j}$$

$$p_{i \cdot} p_{\cdot j} \equiv \sum_{k=1}^n p_{ik} p_{kj}$$

$n \equiv$ no. of unique thyroid nodule depictions

$p_{ij} \equiv$ fraction of n scored i by humans and j by phantom/automation

$w_{ij} \equiv$ weighting factor (1 if $i=j$; 0.5 if $|i-j|=1$;
0 if $|i-j|>1$)

Scoring Phantom Images

- Function of Depth
- Raw Score
 - Resolution Zone includes depth of interest: 1 point
 - 7 total phantoms, 7 max. points
 - Need to map raw scores to clinical scores (1-5)

Results: Kappa Coefficients

LSNR threshold	TAFC fraction correct	Kappa coeffi- cient	agree- ment level
-2	0.7	0.33	fair
-3	0.88	0.58	moderate

Conclusions

- Clinical and Phantom/automation agreement is at least “fair” for an LSNR threshold of -2
- Agreement is “moderate” for an LSNR threshold of -3
- Perhaps the LSNR threshold of -3 is the better choice
- More patient studies required

