

Relationship of DQE to visual image quality

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Outline

- Meaningful metrics
 - search for the “Holy Grail”
- Ideal observer formulation
 - detected versus display data
- Assumptions
 - SKE/BKE imaging task and beyond
- Connection to visual image quality

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Meaningful Metrics

Meaningful Metrics (“Holy Grail”)

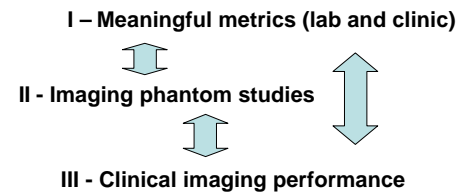
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Meaningful Metrics

“Holy Grail” of Imaging Physics

Connections between:



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Ideal Observer

ICRU Report 54¹

- Represents state-of-the-art of image assessment (up to around 1995) including technical efficacy and diagnostic accuracy
- Technical efficacy approaches used by all manufacturers of digital radiography and mammography equipment^{2,3}

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Meaningful Metrics

What are meaningful metrics?

- Gray scale transfer, resolution, noise and cost (patient dose or imaging time)
- Grounded in statistical decision theory (SDT)^{4,5}
 - task based
- Detective Quantum Efficiency (DQE) as summary measure⁶
 - spatial frequency domain
 - assumptions

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Meaningful Metrics

Detective Quantum Efficiency

Transfer of information in terms of SNR

$$DQE(n) = \frac{SNR_{out}^2(n)}{SNR_{in}^2(n)}$$

Noise Equivalent Quanta

$$NEQ(n) = G^2 MTF^2(n) / NPS(n)$$

$$DQE(n) = \frac{NEQ(n)}{Q}$$

- G, gray-scale transfer
- MTF(n), resolution
- NPS(n), noise
- Q, input quanta (cost)

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Meaningful Metrics

Exposure at detector close to optimum for film-screen (11 mR)

Image of spiculated mass at center of breast

“Holy Grail” of Imaging Physics

DQE

Spatial Frequency (lp/mm)

FFDM

Nyquist Frequency

film/screen

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Ideal Observer

Ideal Observer

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Ideal Observer

Image Formation

- Two stage process: data detection followed by data display⁷

Image Formation

```

graph LR
    Detection[Detection] --> Display[Display]
  
```

- Evaluation of the quality of **detected data**
 - ideal observer from Bayesian decision theory⁴
 - task-based performance

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Ideal Observer

Ideal Observer^{8,9}

- Given image data, **g**.
- Decide which hypothesis (H_1 or H_2).

Hypotheses

No signal, H_1

Signal, H_2

image data, **g**

3. Using Bayes theorem to form likelihood ratio, L, as decision scalar.

$$L = p(\mathbf{g} | H_2) / p(\mathbf{g} | H_1)$$

4. Make assumptions.

- linear, shift invariant imaging system
- signal and background known exactly (SKE/BKE)
- additive, zero-mean, Gaussian distributed noise
- low-contrast signal

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Ideal Observer

$$L = (\mathbf{D} \bar{\mathbf{g}}^t \mathbf{C}_n^{-1}) \mathbf{g}$$

- Expected Difference Signal (\mathbf{Dg})
- System Noise (\mathbf{C}_n , covariance matrix)

5. Calculate figure-of-merit from mean and variance of decision scalar.

6. Estimate quality of detected data in terms of SNR^2 of ideal observer.

Ideal Observer's FOM for SKE/BKE tasks

$$SNR_1^2 = \mathbf{D} \bar{\mathbf{g}}^t \mathbf{C}_n^{-1} \mathbf{D} \bar{\mathbf{g}}$$

Upper bound for human and machine performance!!!¹⁰

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Ideal Observer

Connection to NEQ/DQE

Spatial Domain:

- Df , Expected Input Signal
- H , System Transfer Function

$$D\bar{g} = HD\bar{f}$$

$$SNR_i^2 = D\bar{f}^T (H^T C_n^{-1} H) D\bar{f} \quad - (H^T C_n^{-1} H), \text{ Image noise referred to object domain} == NEQ(n) !^1$$

Spatial Frequency Domain (previous assumptions, stationary noise and continuous mathematics!!)

$$SNR_i^2 = G^2 \int_0^\infty \frac{|Df(n)|^2 MTF^2(n)}{W_n(n)} dn$$

- $G^2 MTF^2/W_n$, Image noise referred to object domain == $NEQ(n) !^1$

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Meaningful Metrics

"Holy Grail" of Imaging Physics

Connections between:

- I - Meaningful metrics (lab and clinic)
- II - Imaging phantom studies
- III - Clinical imaging performance

Assumptions:

- . linear, shift invariant imaging system
- . signal and background known exactly (SKE/BKE)
- . additive, zero-mean, Gaussian distributed noise
- . low-contrast signal
- . stationary noise

Imaging Phantoms:

- . ACR/MAP
- . CDMAM
- . etc

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Ideal Observer

Connection to imaging phantom studies^{11,12}

- Fuji 9000 Reader
- Fuji HR-V imaging plates
 - 18 cm x 24 cm
 - 0.1 mm pixel
- Prediction from lab (solid lines)
 - $SNR = 3$ and 5
- Human performance

CDMAM contrast detail imaging phantom – 4 AFC

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Ideal Observer

Connection to imaging phantoms – ACR/MAP

- Data on G , MTF and W_n from literature¹³
- Mammo system
 - Mo/Mo
 - Ortho M/Min R
 - $OD = 1.26$
- Speck constituents
- Calculate SNR_i

RMI 156			
Group	d (mm)	Contrast	SNR_i
1	0.54	0.32	36 (34)*
2	0.4	0.23	19 (20)*
3	0.32	0.18	12 (10)*
4	0.24	0.13	6
5	0.16	0.09	2

* reference 14

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Assumptions

Assumptions?

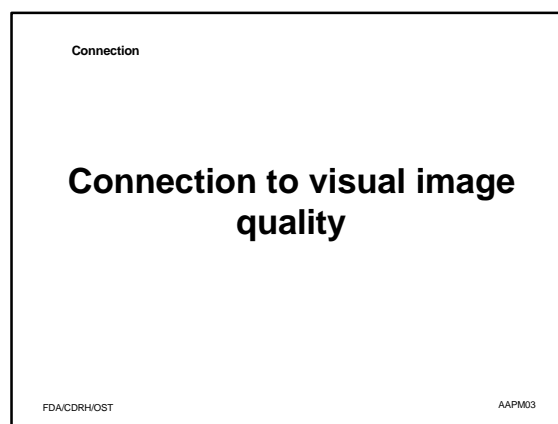
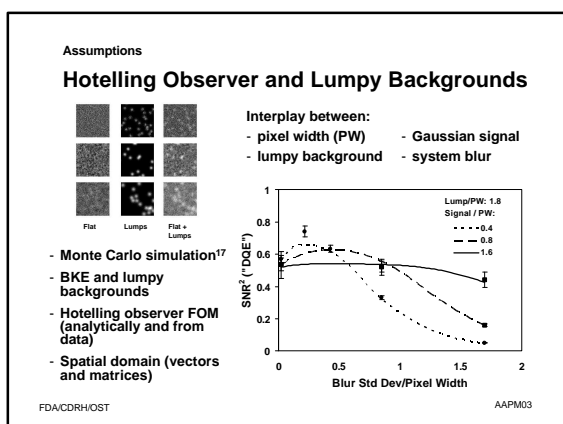
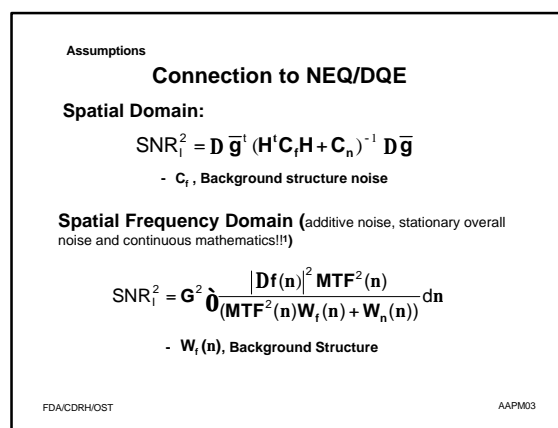
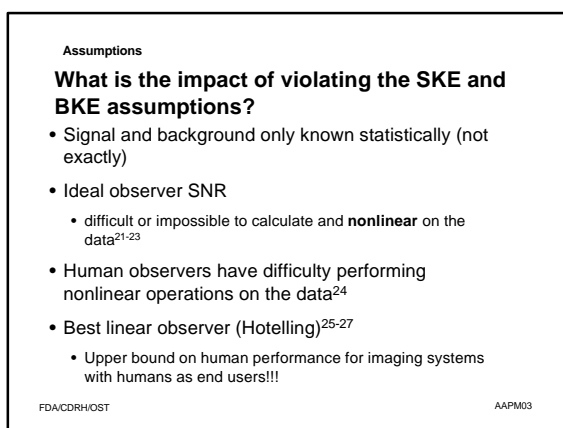
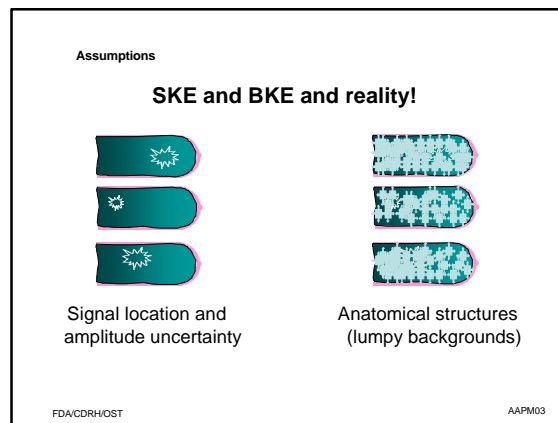
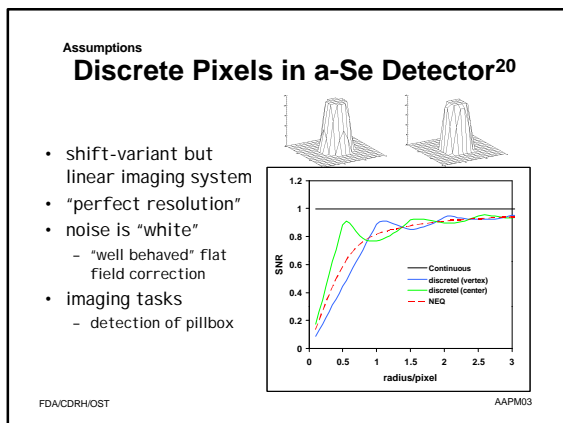
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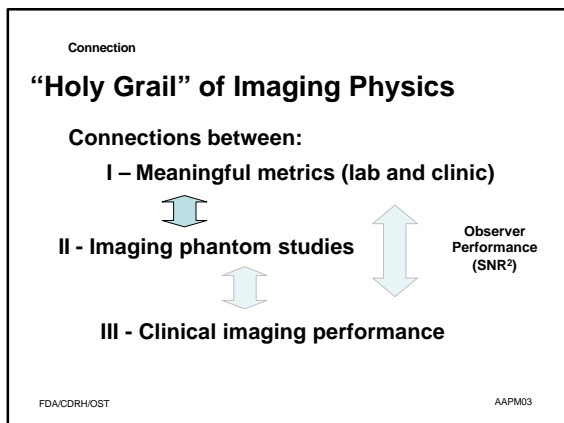
Assumptions

What is the impact of violating the assumption on shift-invariance?

- Digital imaging systems are not shift invariant (Giger and Doi)¹⁵
- Current FOMs (SNR^2 using NEQ, DQE) not cognizant of signal position
 - spatial vs. spatial frequency domain (aliasing)
- Current research topic¹⁶⁻¹⁹

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Connection

How do we make connection to visual image quality?

- Lots of literature on model observers capable of handling non SKE/BKE imaging tasks such as lumpy backgrounds
 - Hotelling (upper bound), non-prewhitening (lower bound)
 - observers bracket human performance
- System design and optimization advantages
- Comparison to human performance
 - ROC analysis

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Conclusions

- Meaningful metrics are available and important to measure
 - search for the “Holy Grail” continues
- Observer FOM provides means for system performance assessment and optimization (detected data)
 - bounds on human performance
- Connection to visual image quality

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